



N-ways to GPU Programming Bootcamp

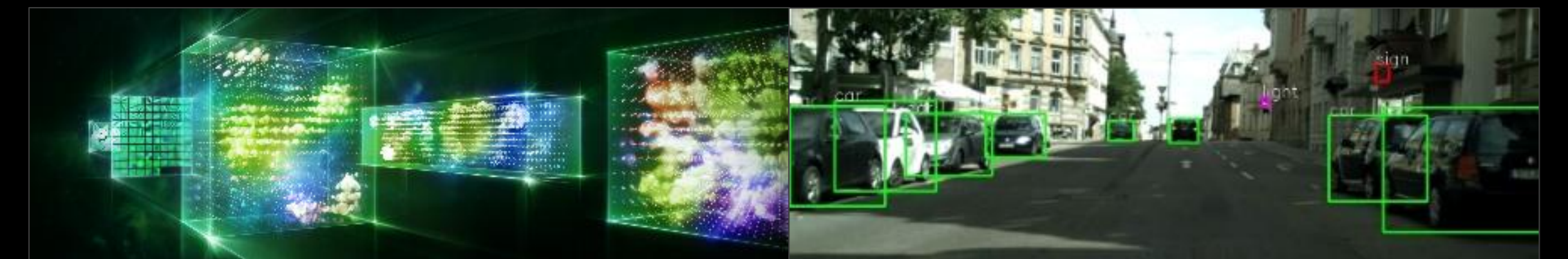
Accelerating Python on GPUs

9th April 2025

Paul Graham, Senior Solutions Architect, NVIDIA

pgraham@nvidia.com

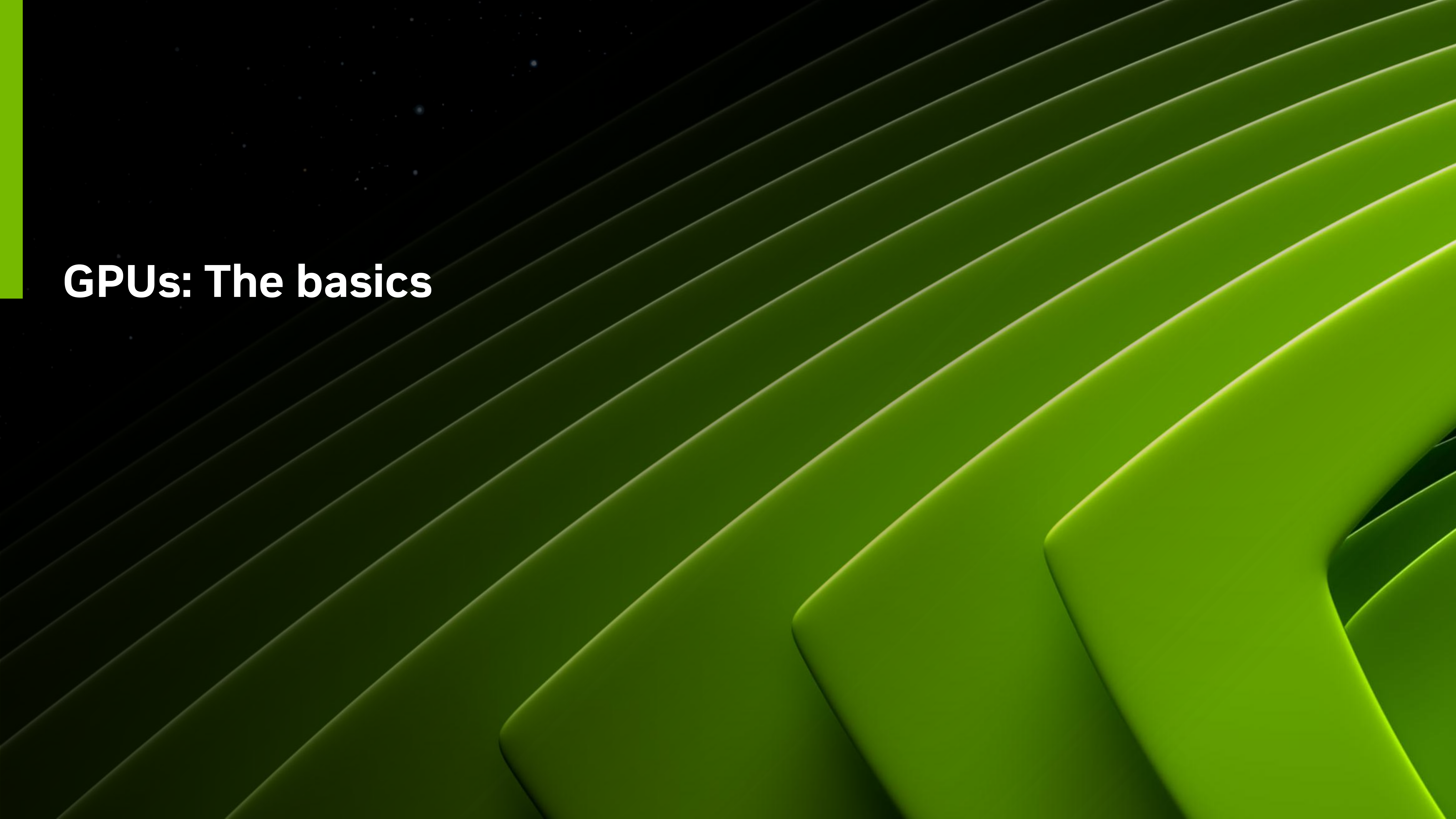
NVIDIA



GPU Computing

Computer Graphics

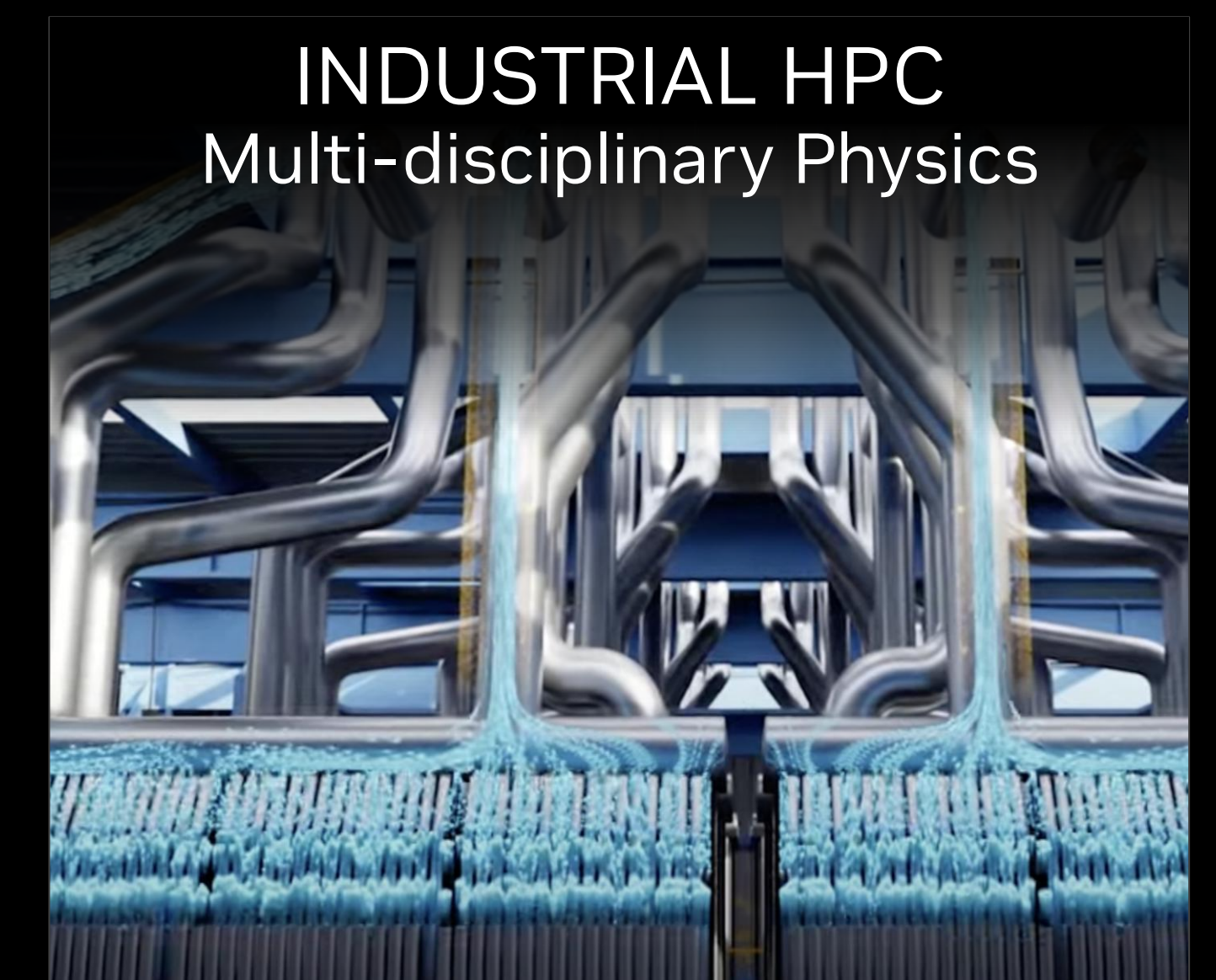
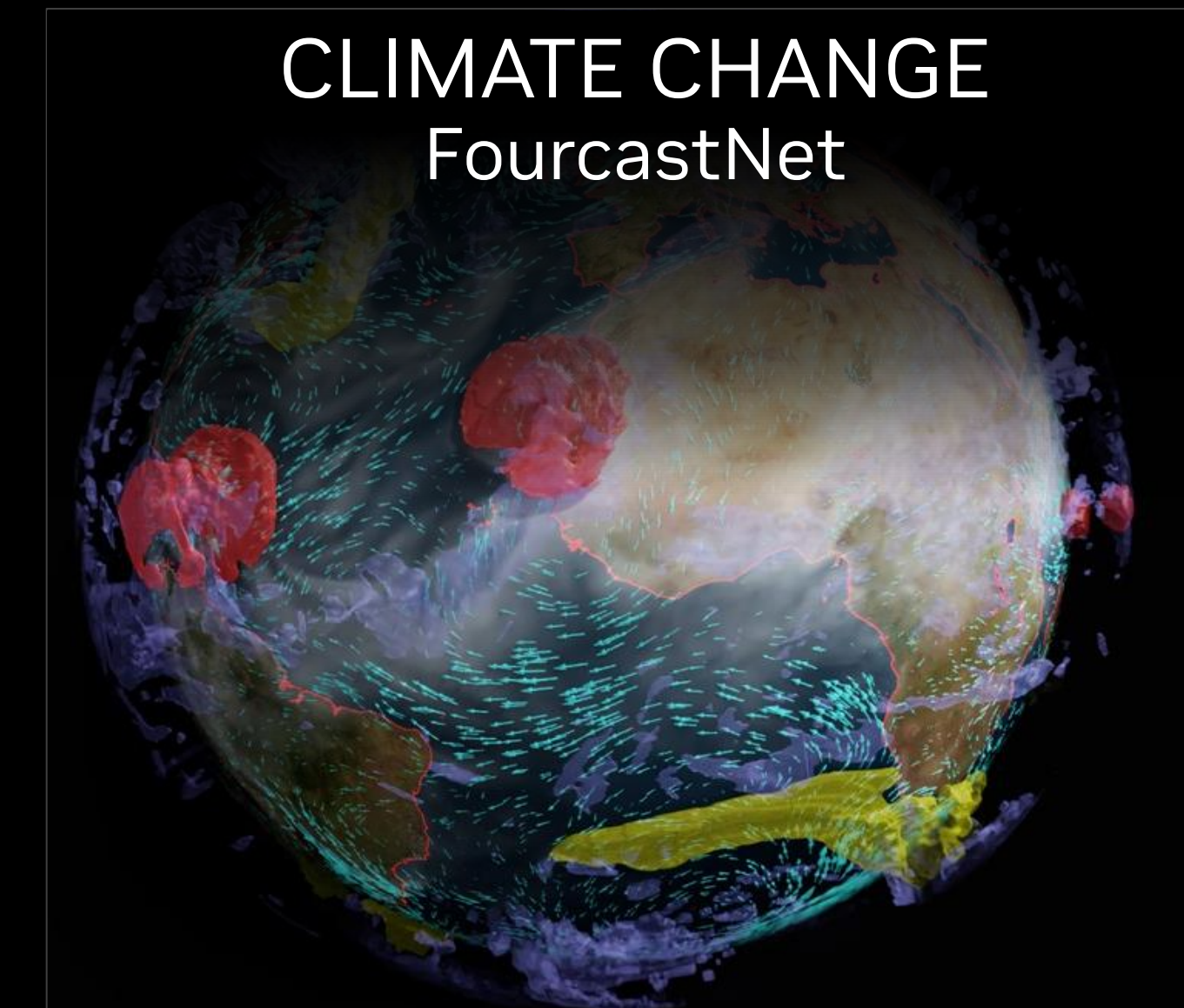
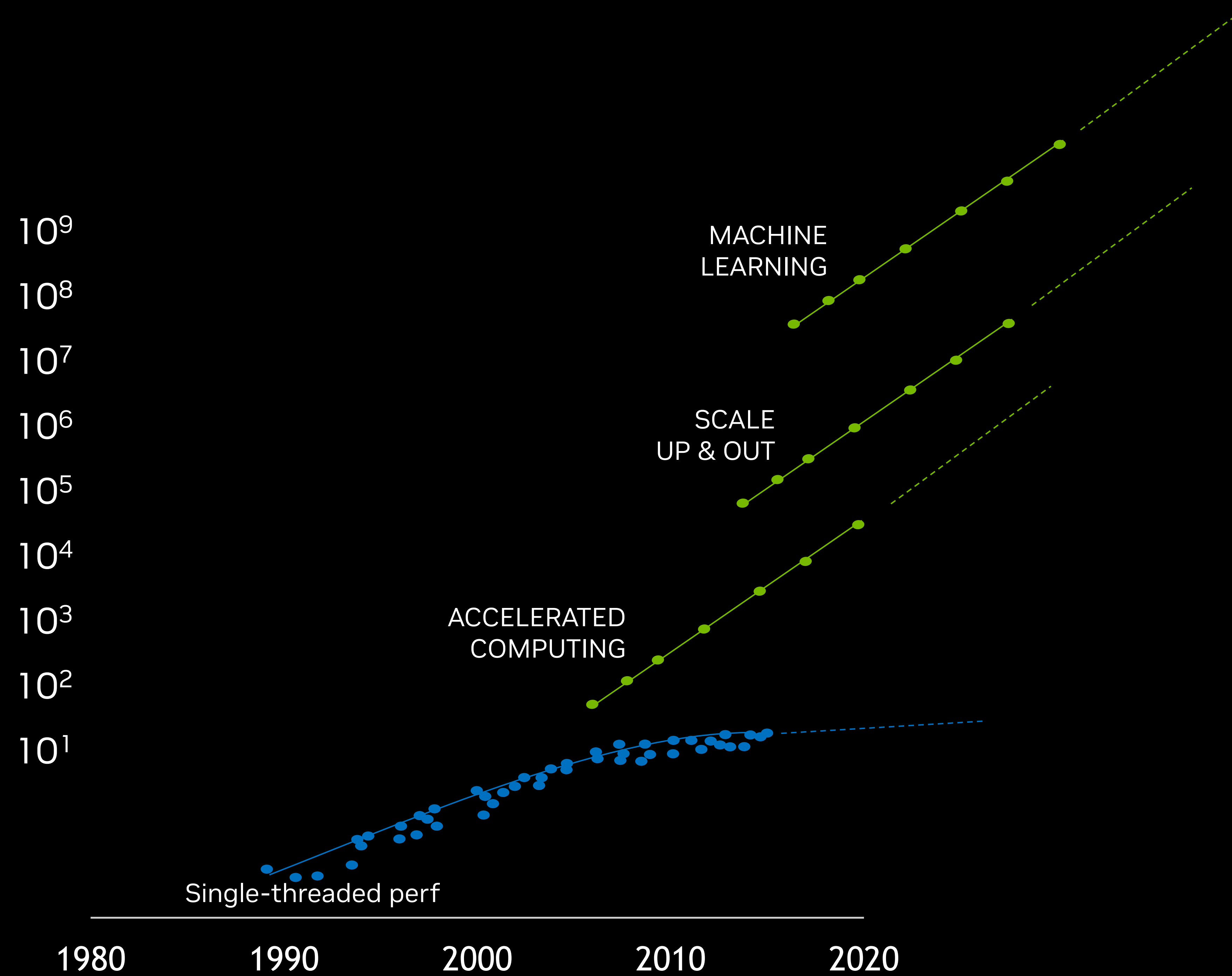
Artificial Intelligence



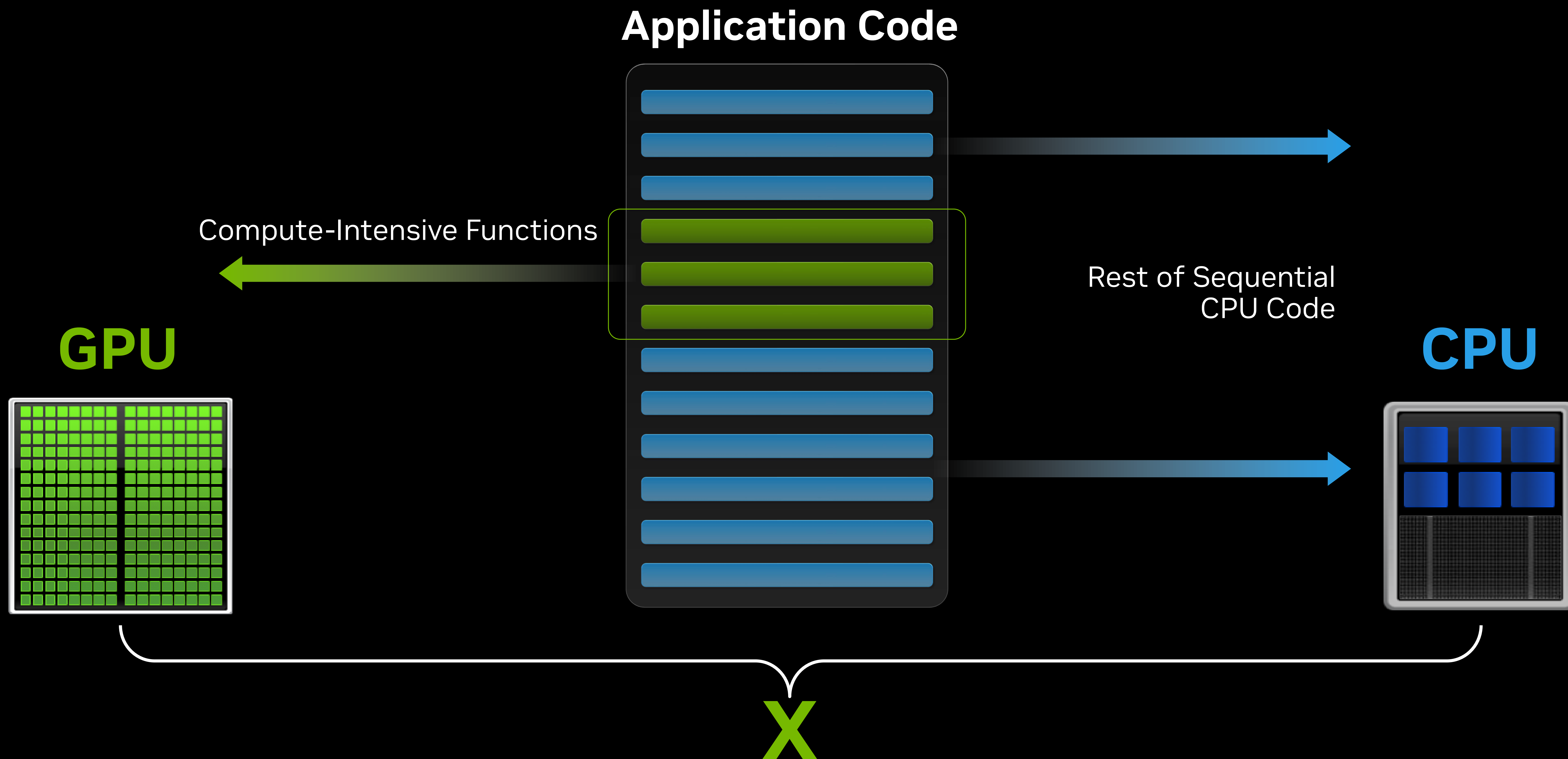
GPUs: The basics

Million-X Speedup for Innovation and Discovery

Simulation + AI

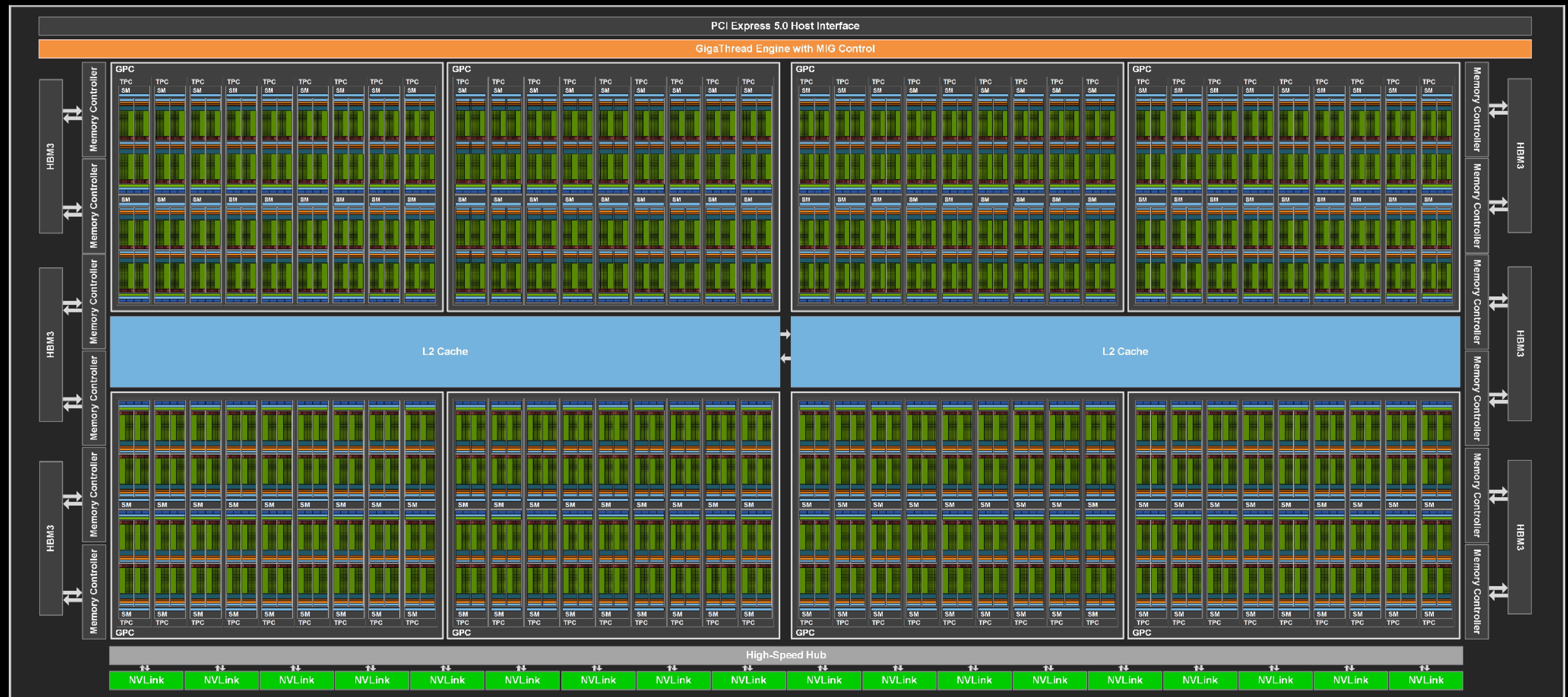


Small Changes, Big Speed-up



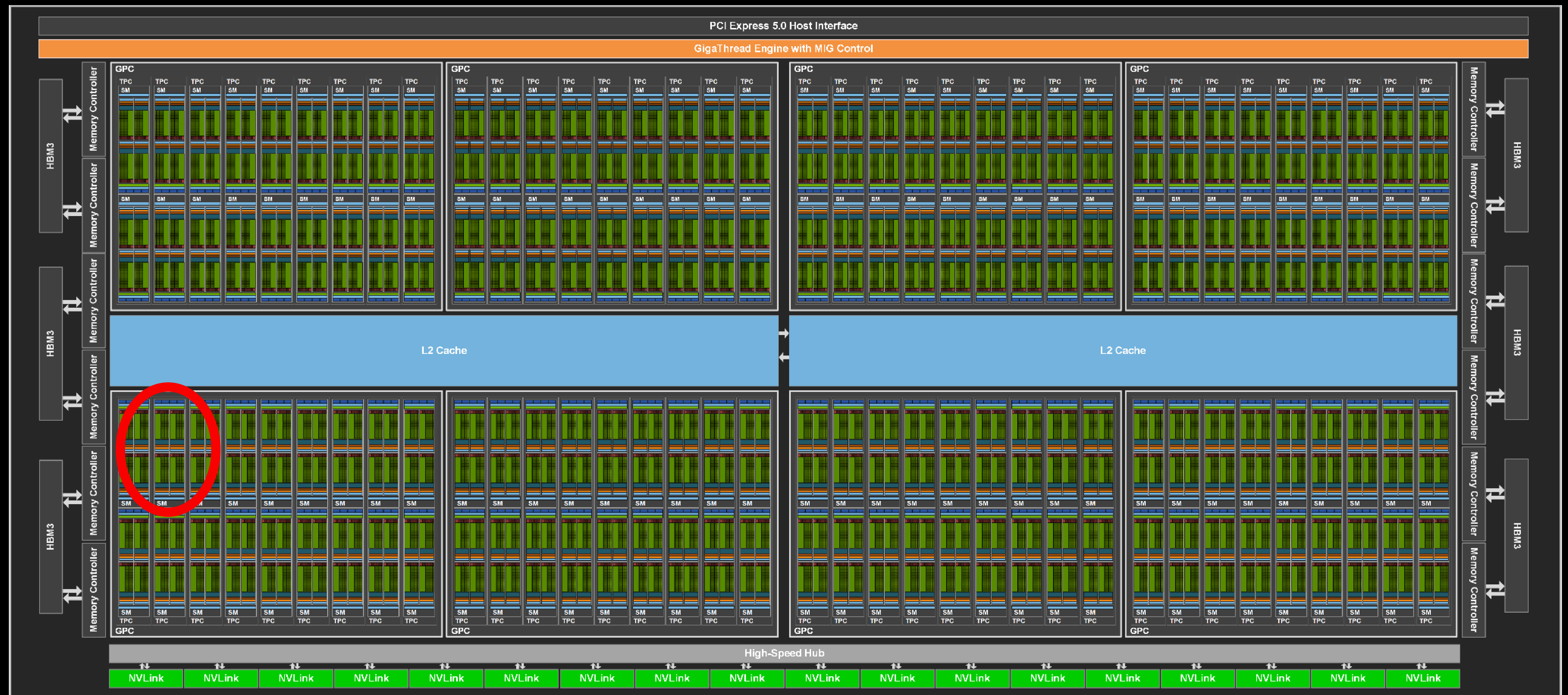
GH100 GPU Architecture

<https://resources.nvidia.com/en-us-tensor-core/gtc22-whitepaper-hopper>



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ht

ecture

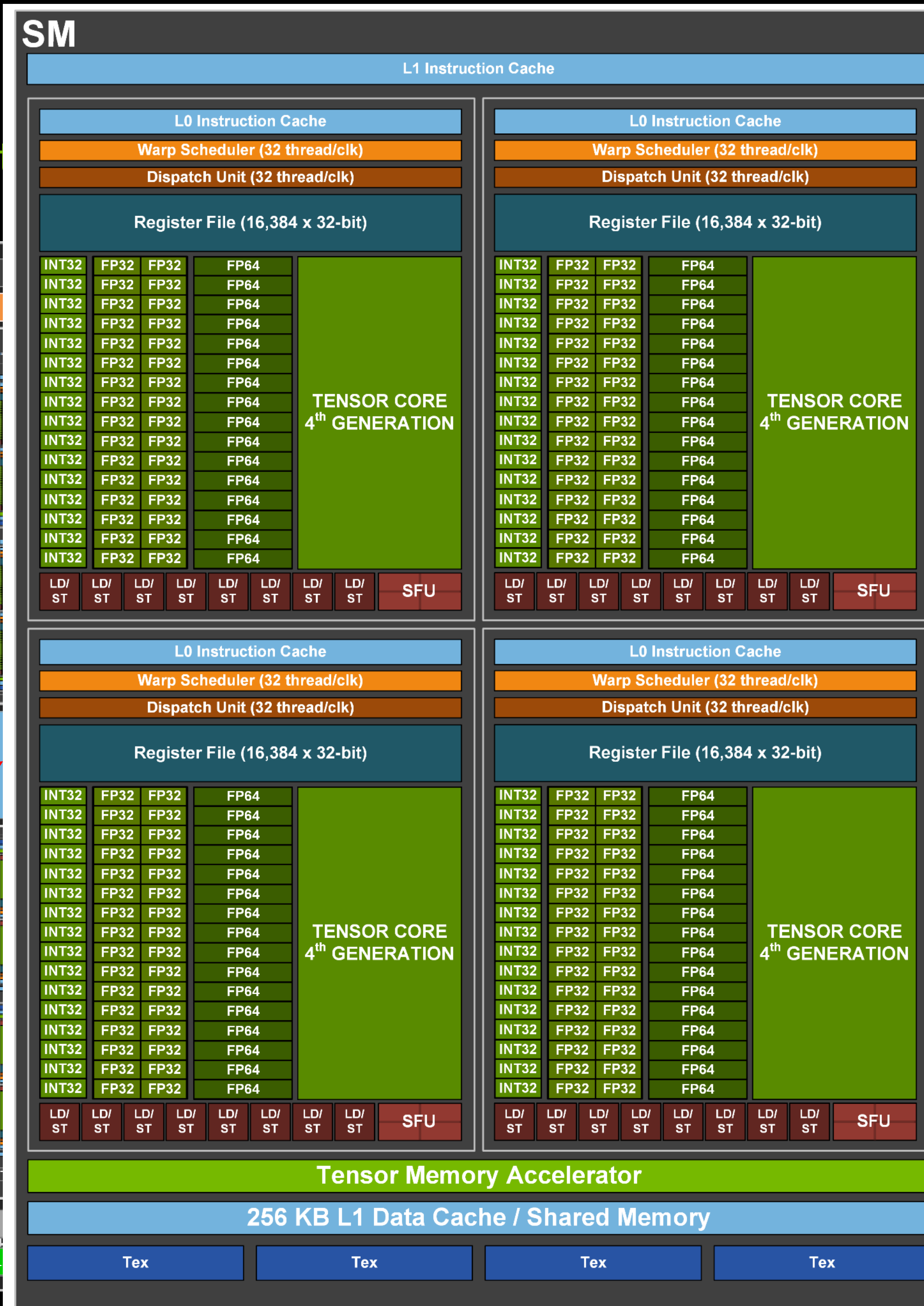
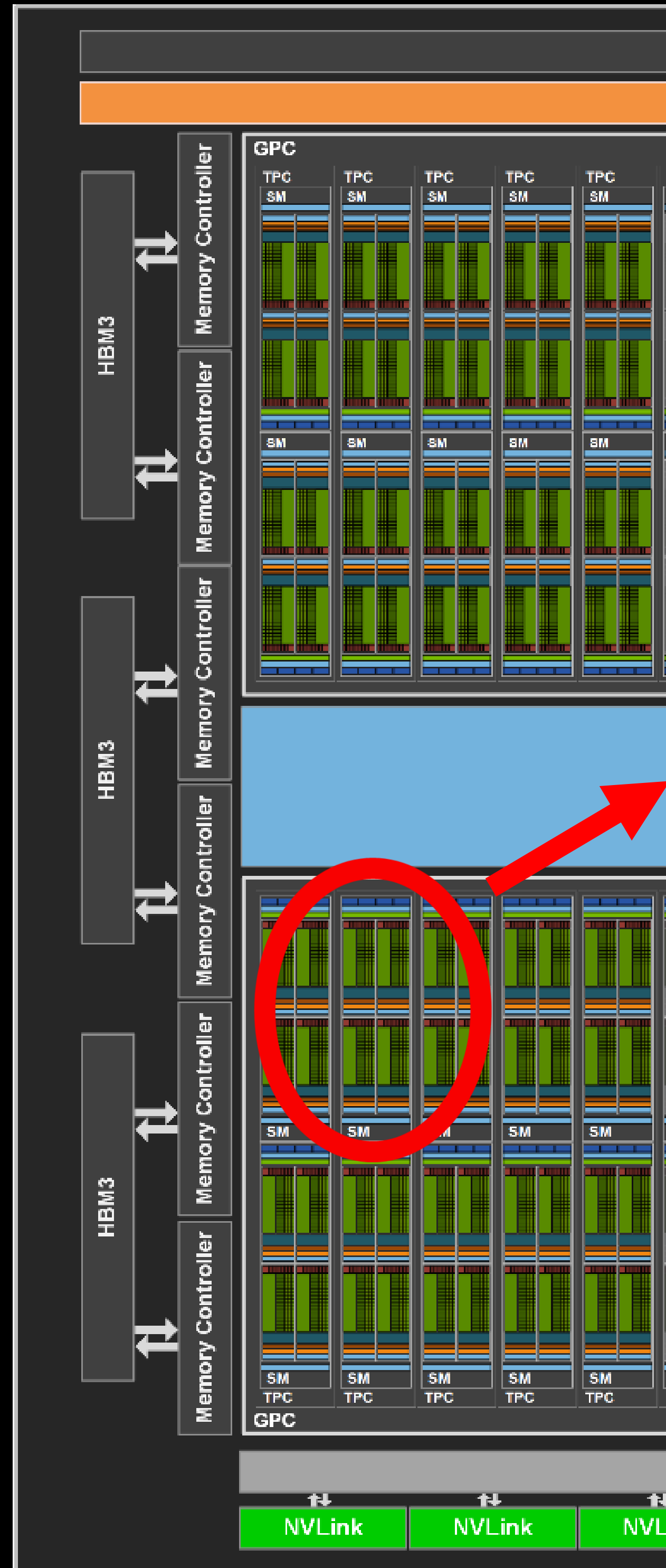
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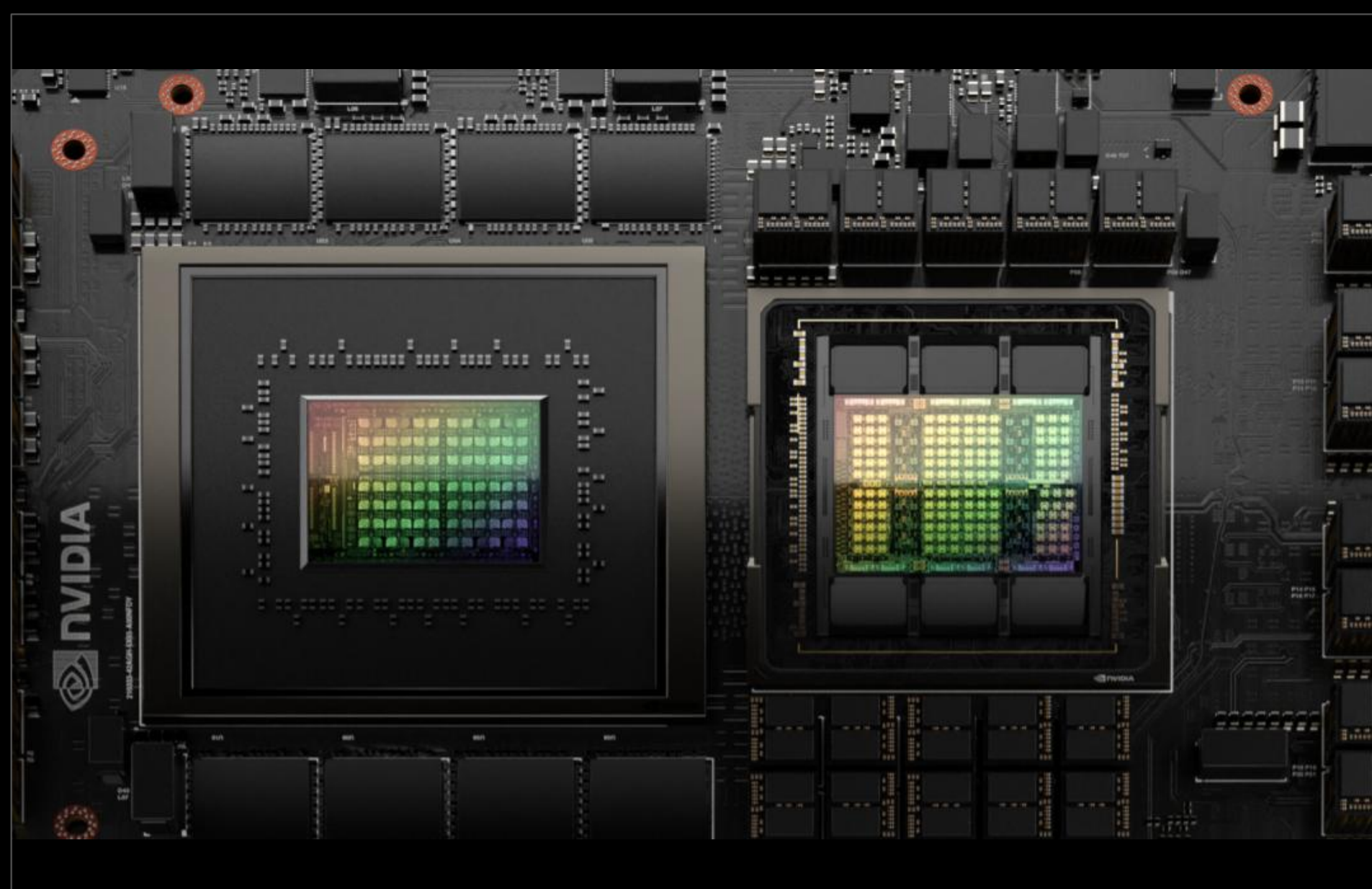
https://nvidia

ecture

e/gtc22-whitepaper-hopper



- 132 of these in the H100 SXM5 GPU
- > 16000 FP32 cores in total
- We usually want number of threads >> num cores
- So we need a lot of threads!



Multi-die



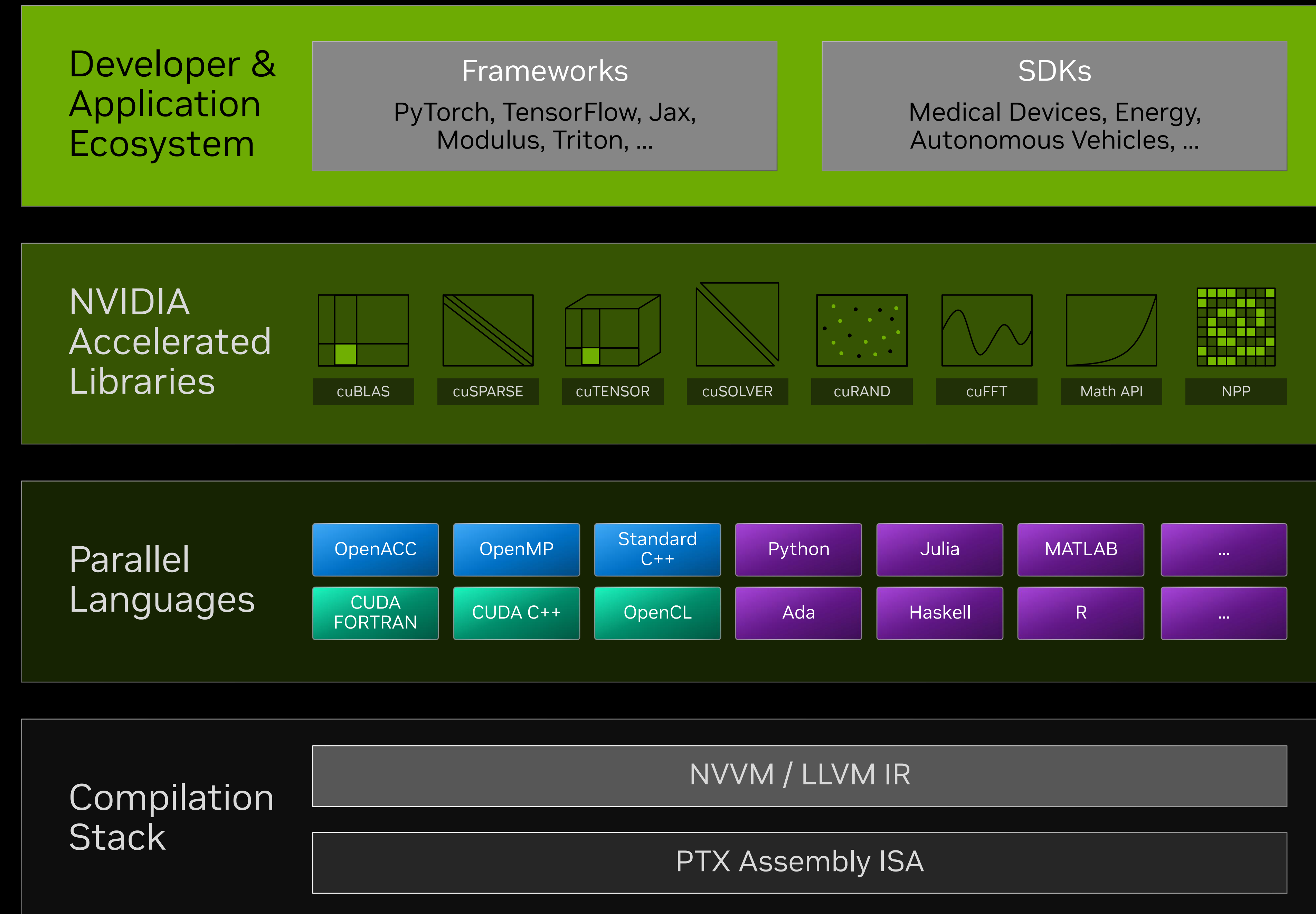
Multi-chip



Multi-node

The CUDA Platform

Target the abstraction layer that works best for your application

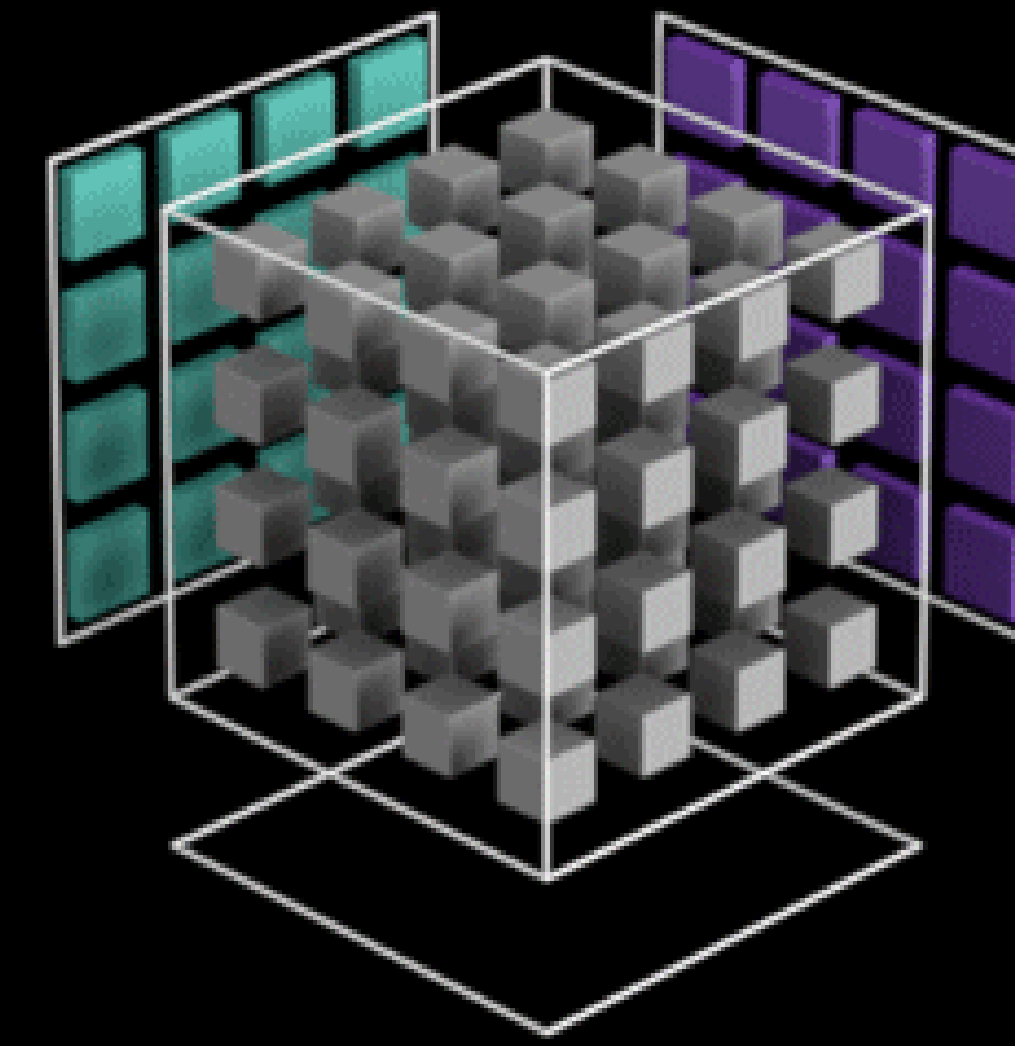


Tensor Cores

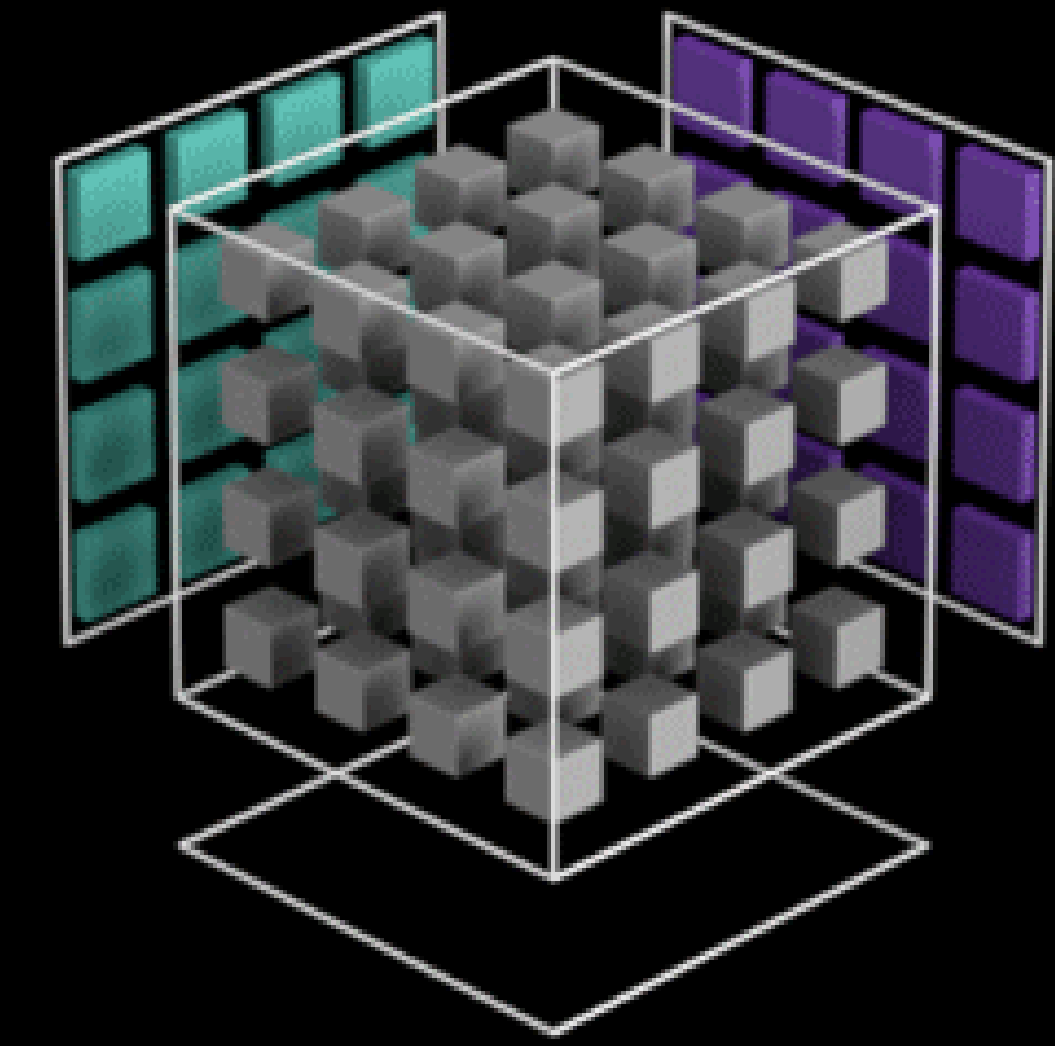
Hardware for Matrix Multiply and Accumulate operations

- Perform several MMA calcs per clock cycle
- Introduced in the V100
 - FP32 in, FP32 out (accumulate)
 - FP16 multiply
- Turing added int8, int4, int1 calculations
- Ampere (A100)
 - Full FP64 MMA
 - Bfloat16, Tensor Float 32
- Hopper (H100)
 - FP8
 - Transformer Engine

PASCAL



VOLTA TENSOR CORES



cuDNN Library, CUTLASS

Exploiting Tensor Cores

cuDNN - Accelerating deep learning primitives

Key Features

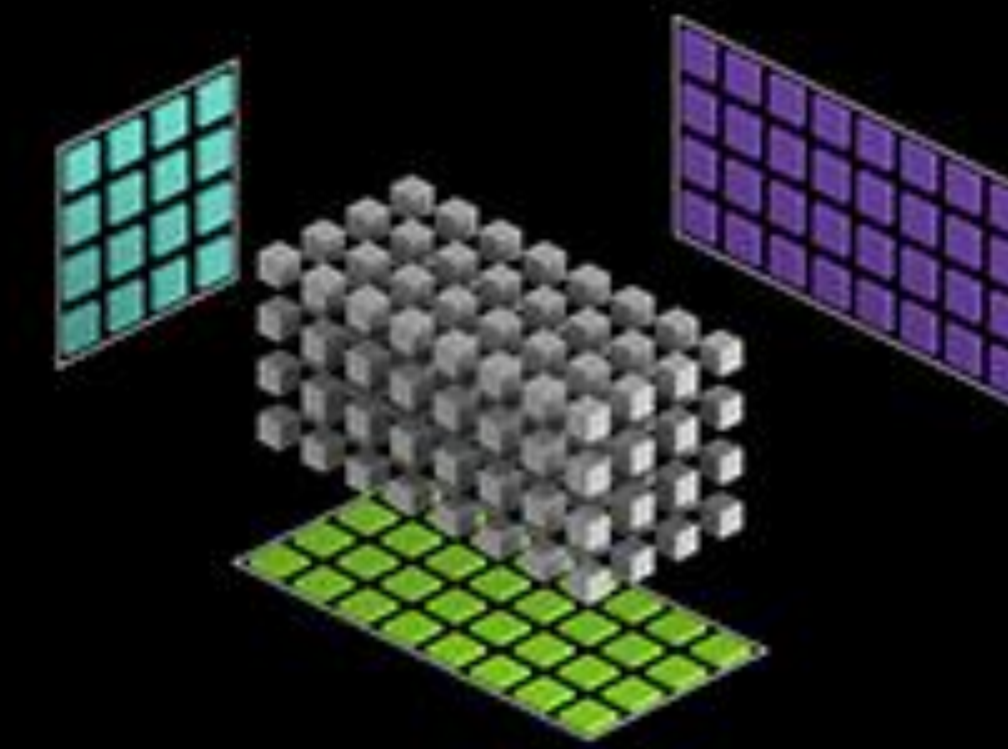
- Tensor Core acceleration for all popular convolutions
- Supports FP32, FP16, BF16 and TF32 floating point formats and INT8, and UINT8 integer formats
- Arbitrary dimension ordering, striding, and sub-regions for 4d tensors means easy integration into any neural net implementation

CUTLASS – Tensor Core Programming Model

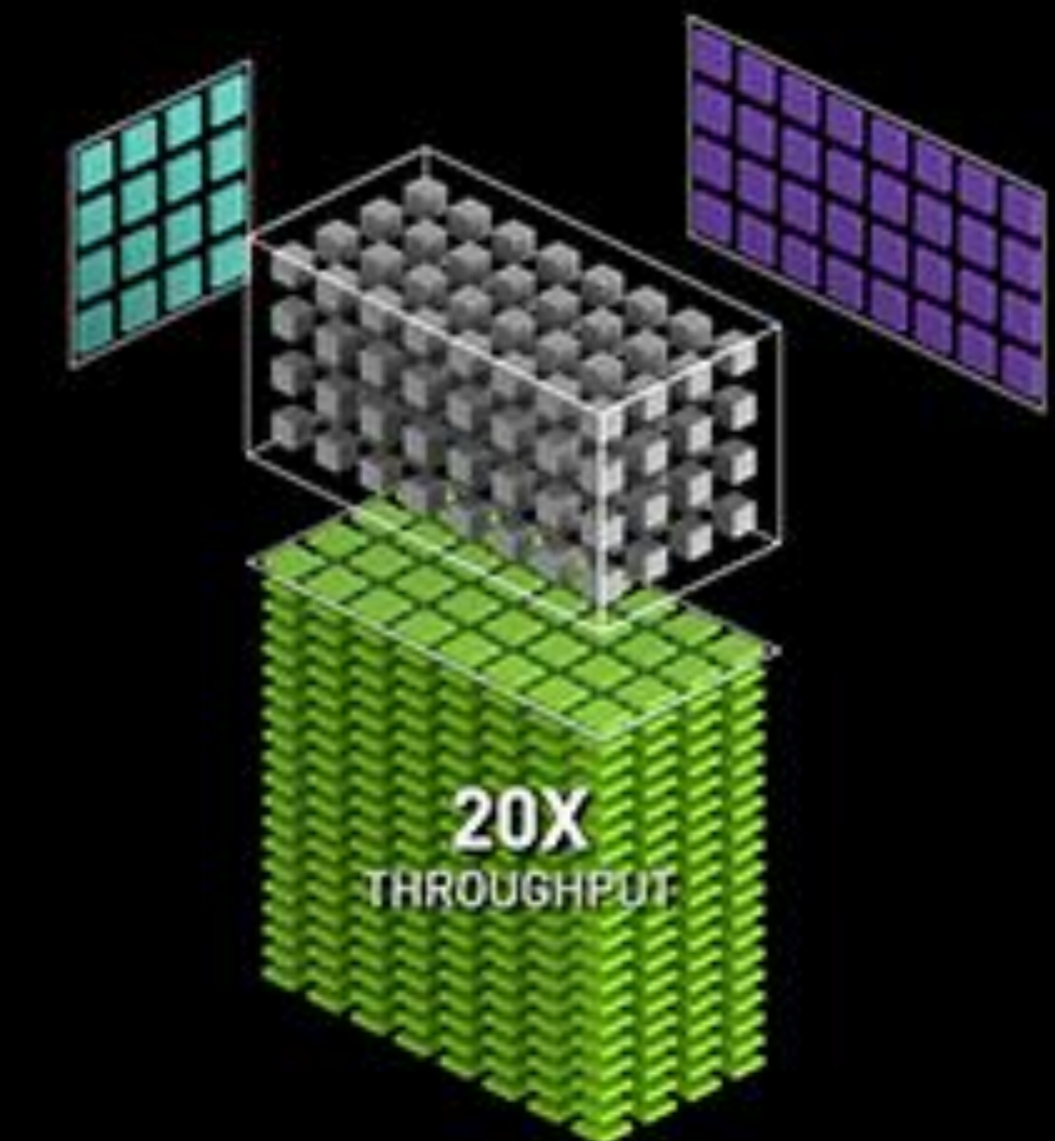
- Warp-Level GEMM and Reusable Components for Linear Algebra Kernels in CUDA
- Has Python interfaces



NVIDIA V100 FP32



NVIDIA A100 Tensor Core TF32 with Sparsity





Frameworks and Libraries

Many Frameworks ... All With Python Support

[NVIDIA Launchpad](#) — free hands-on labs

- [cuOpt](#) – accelerated optimisation engine e.g. for Logistics and Route Optimisation
- [Isaac Sim](#) – robotics simulation toolkit – building virtual worlds for training robots
- [Riva](#) – speech AI services: transcription, translation, text to voice ...
- [Clara](#) – AI powered solutions for healthcare and life sciences e.g. Genomics, Medical Instruments
- [Holoscan](#) – acceleration of sensor data processing pipelines
- [Merlin](#) – end to end system for recommender frameworks
- [NeMo](#) – framework for building and deploying generative AI models
- [TAO toolkit](#) – for transfer learning
- [DeepStream SDK](#) – for streaming IVA applications
- [Modulus](#) – PyTorch-based framework for Physics-informed Neural Networks (PINNs)
- ...



[Isaac Sim](#)

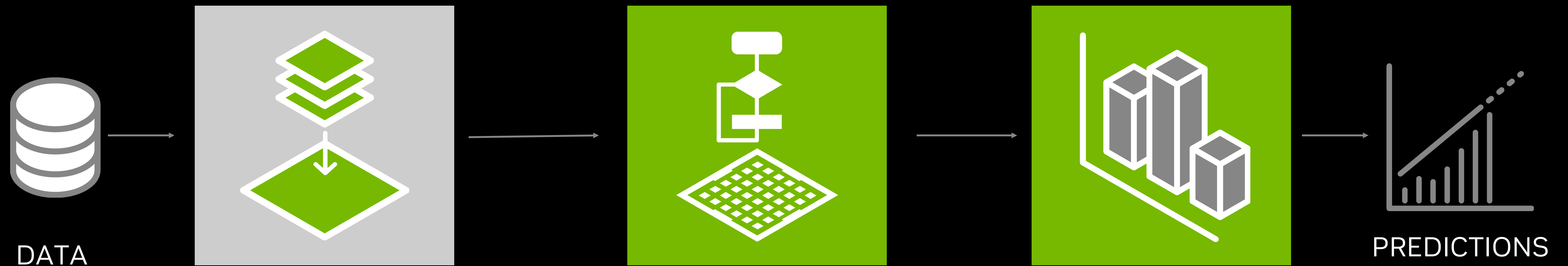


[NVIDIA Modulus and Omniverse](#)

RAPIDS

GPU-accelerated data science workflow

[RAPIDS.ai](https://rapids.ai)



DATA PREPARATION - ETL

cuDF: Python drop-in **pandas** replacement built on CUDA.
GPU-accelerated Spark

MODEL TRAINING

cuML: GPU-acceleration of popular ML algorithms e.g. **XGBoost**
Easy-to-adopt, **scikit-learn** like interface

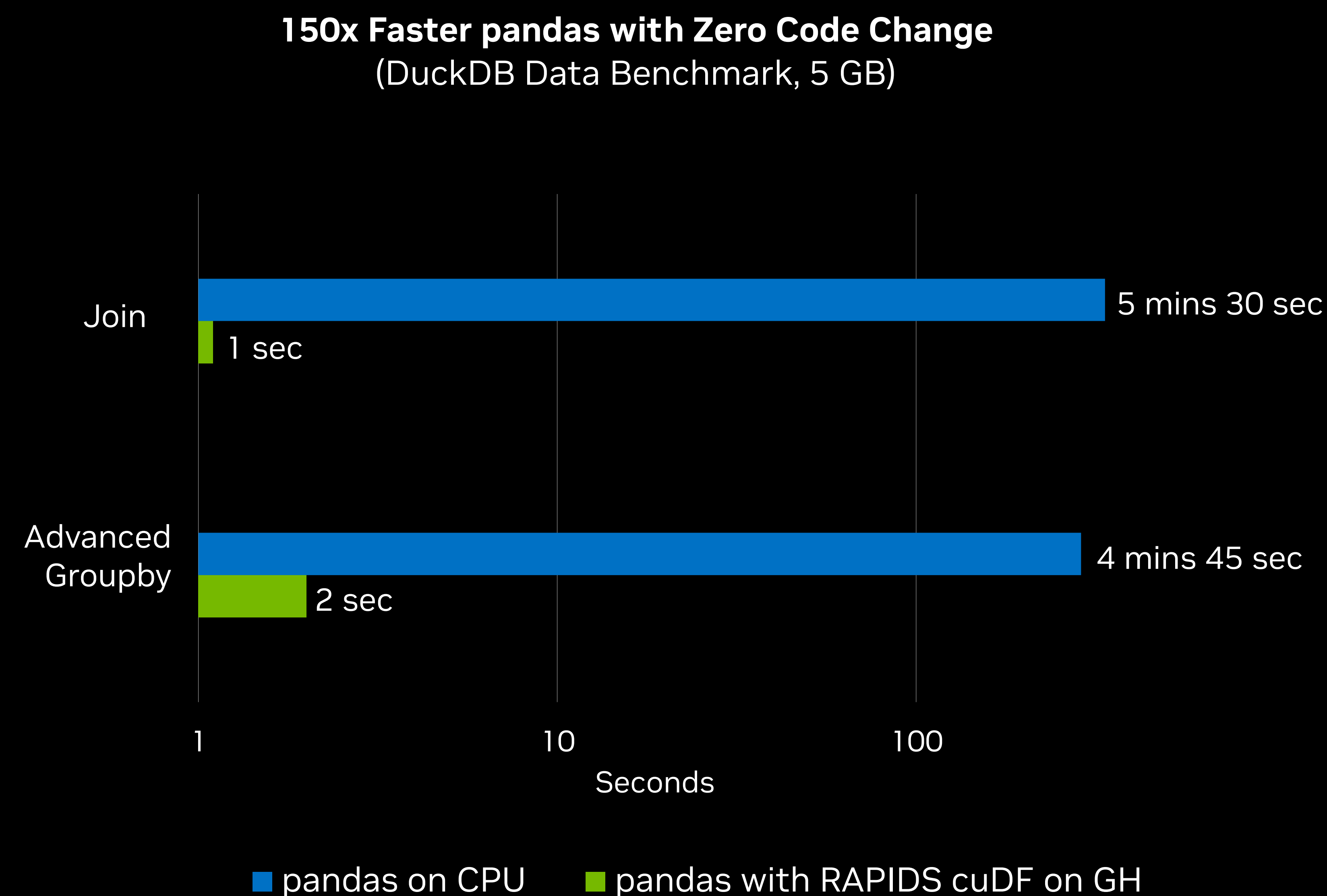
VISUALIZATION

Effortless exploration of datasets, billions of records in milliseconds
Dynamic interaction with data = faster ML model development

Announcing RAPIDS cuDF Accelerates pandas with Zero Code Change

World's fastest data analytics with pandas

- 150x Faster than CPU-only
- Unified workflow on CPUs and GPUs across laptops, workstation & datacenter
- Compatible with third-party libraries built on pandas
- [Available today](#) in Open Beta and NVIDIA AI Enterprise support coming soon



NVIDIA Grace Hopper vs. Intel Xeon Platinum 8480CL CPU



- See also [cuGraph](#) – focussed on GPU-accelerated graph analytics including GNNs and **NetworkX**: [blog](#)
- Has a zero code change backend for **NetworkX**, [nx-cugraph](#)

**** NEW ****

nvmath-python

- Bringing NVIDIA maths libraries to the Python ecosystem
 - Performance, productivity, interoperability
 - cuBLAS, cuFFT ... without need for C/C++ bindings
 - Kernel fusion for efficiency
 - Kernel autotuning
 - Interoperable – e.g. can pass PyTorch data objects directly to maths libraries
 - Supports Python logging
- [Demo](#) from GTC session "Deep Dive into Math Libraries"

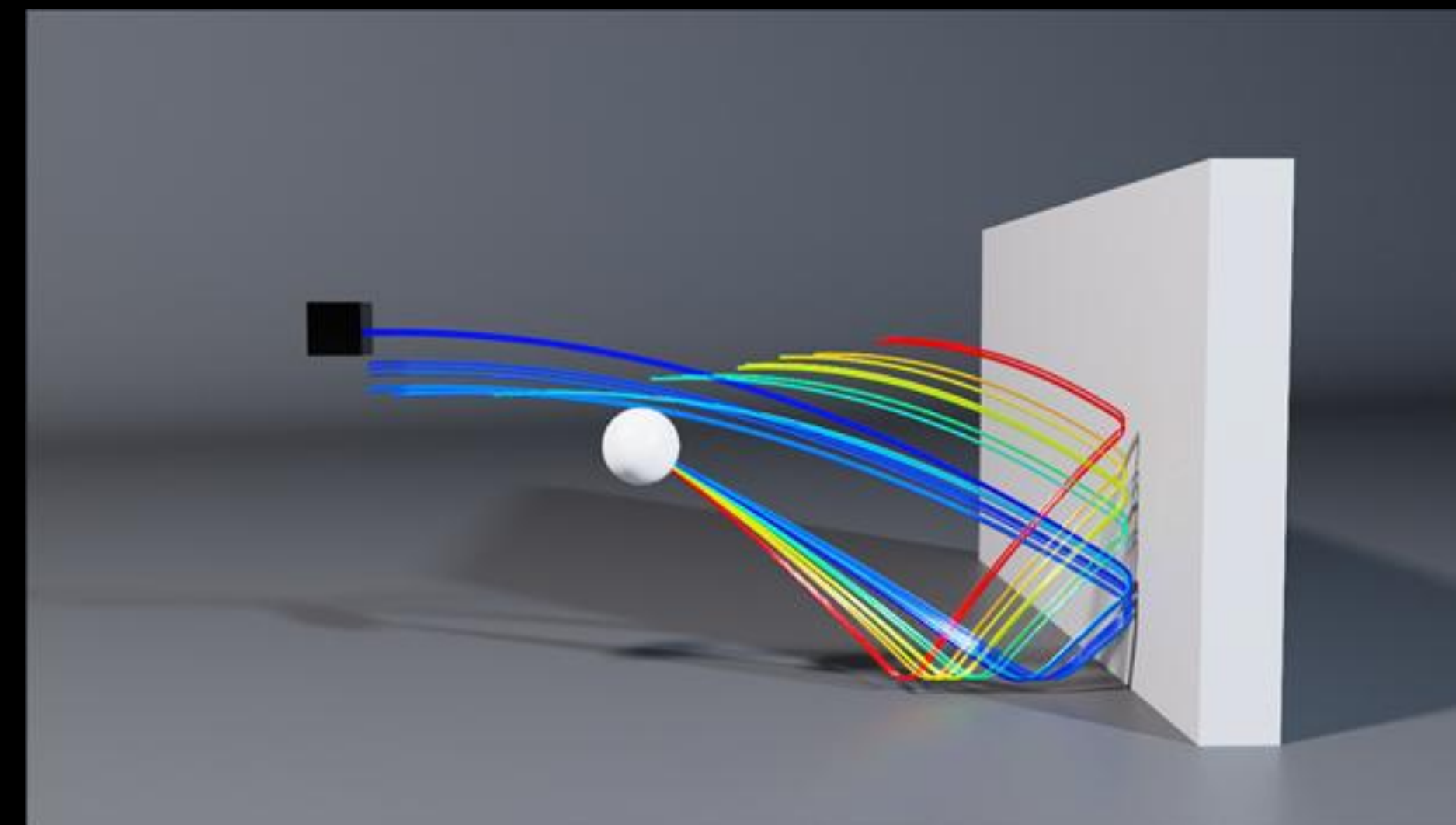
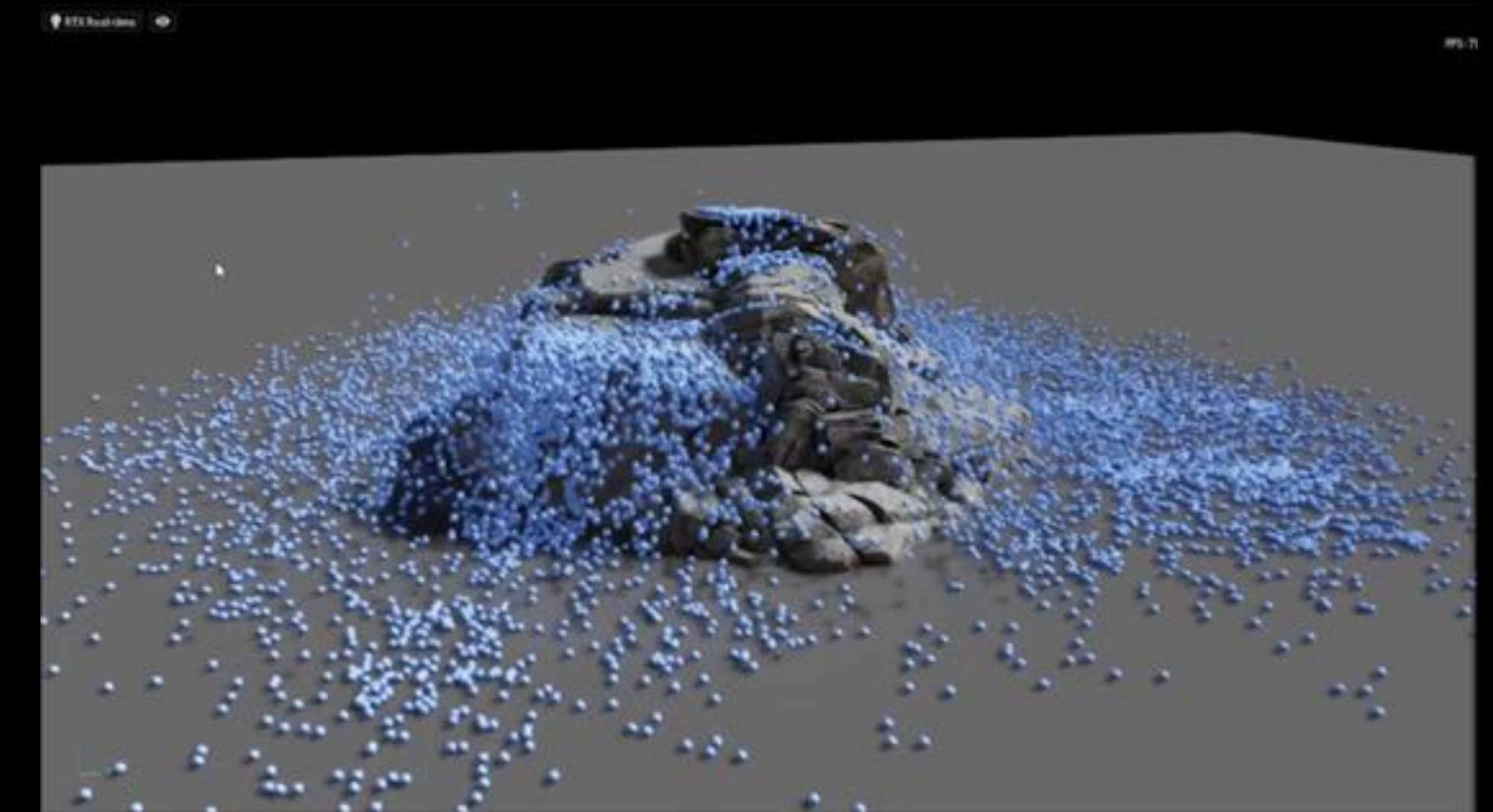
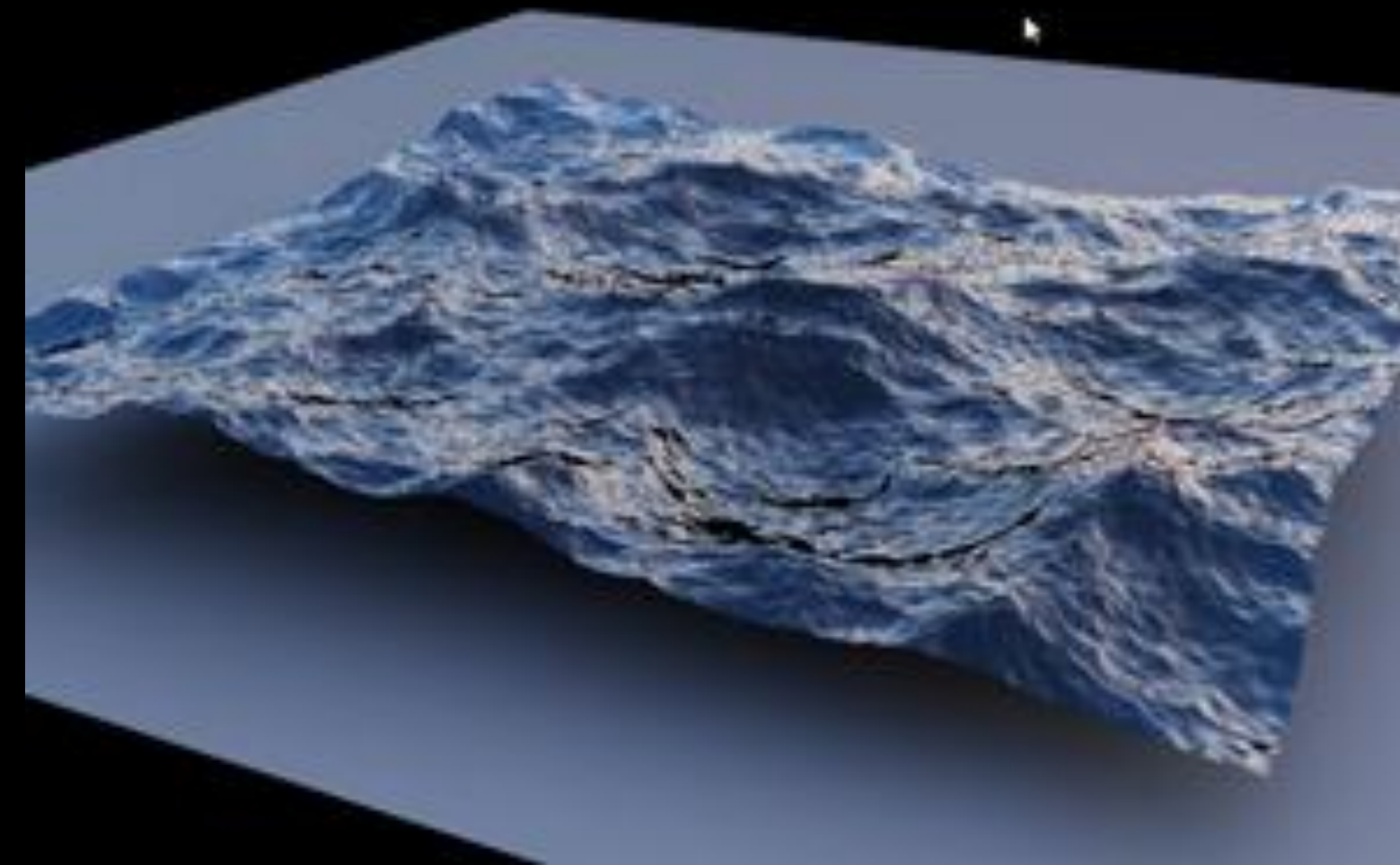
Polars now GPU accelerated

- [open beta](#)
- Python DataFrame library
 - Aimed at 10s-100s GB workloads on single machine
 - Now accelerated on NVIDIA GPUs
 - Up to 13x speed up over CPUs
 - Makes use of cuDF from RAPIDS
- Technical [blog](#)
- Intro notebooks: [Colab](#) | [GitHub](#)

**** NEW ****

NVIDIA Warp

- Differentiable Spatial Computing for Python
- Developer framework for building simulation workflows
 - High-level data structures
 - Meshes
 - Sparse volumes
 - Hash grids – useful for smoothed particle hydrodynamics
 - Automatic differentiation
 - Memory model supports zero-copy data views between tensor-based frameworks
- [Blog](#)
- [Tutorial](#): Introduction to NVIDIA Warp in Omniverse



Programming directly for GPUs

Programming the NVIDIA Platform

LANGUAGE FEATURES AND DROP-IN LIBRARIES

ISO C++, ISO Fortran, CuPy, cuPyNumeric

```
std::transform(par, x, x+n, y, y,  
    [=] (float x, float y){ return y +  
    a*x; }  
);
```

```
do concurrent (i = 1:n)  
    y(i) = y(i) + a*x(i)  
enddo
```

```
import cupynumeric as np  
...  
def saxpy(a, x, y):  
    y[:] += a*x
```

INCREMENTAL PORTABLE OPTIMIZATION

OpenACC, OpenMP, Numba

```
#pragma acc data copy(x,y) {  
...  
std::transform(par, x, x+n, y, y,  
    [=] (float x, float y){  
        return y + a*x;  
    });  
...  
}
```

```
@vectorize(['float64(float64, float64,  
float64)'], target='cuda')  
def saxpy_ufunc(a, x, y):  
    return a*x+y;
```

PLATFORM SPECIALIZATION

CUDA, Numba, PyCUDA

```
@cuda.jit(void(float32, float 32[:],  
float32[:], float32[:]))  
def saxpy(a, x, y, out):  
    idx = cuda.grid(1)  
    out[idx] = a * x[idx] + y[idx]
```

```
mod = cuda.SourceModule("""  
__global__  
void saxpy(int n, float a,  
    float *x, float *y) {  
    int i = blockIdx.x*blockDim.x +  
        threadIdx.x;  
    if (i < n) y[i] += a*x[i];  
}  
""")
```

ACCELERATION LIBRARIES

Core

Math

Communication

Data Analytics

AI

Quantum

cuPy – NumPy Compatible Library for GPU

Key Features

- Supports a subset of the `numpy.ndarray` interface
- Also makes use of NVIDIA libraries: cuBLAS, cuRAND, cuSolver ...
- Can make use of Unified Memory

CPU

```
import numpy as np

def saxpy(a, x, y):
    return a * x + y

a = 3.141
x = np.random.rand(1024, 2048)
y = np.random.rand(1024, 2048)

result = saxpy(a, x, y)
```

GPU

```
import cupy as cp

def saxpy(a, x, y):
    return a * x + y

a = 3.141
x = cp.random.rand(1024, 2048)
y = cp.random.rand(1024, 2048)

result = saxpy(a, x, y)
```

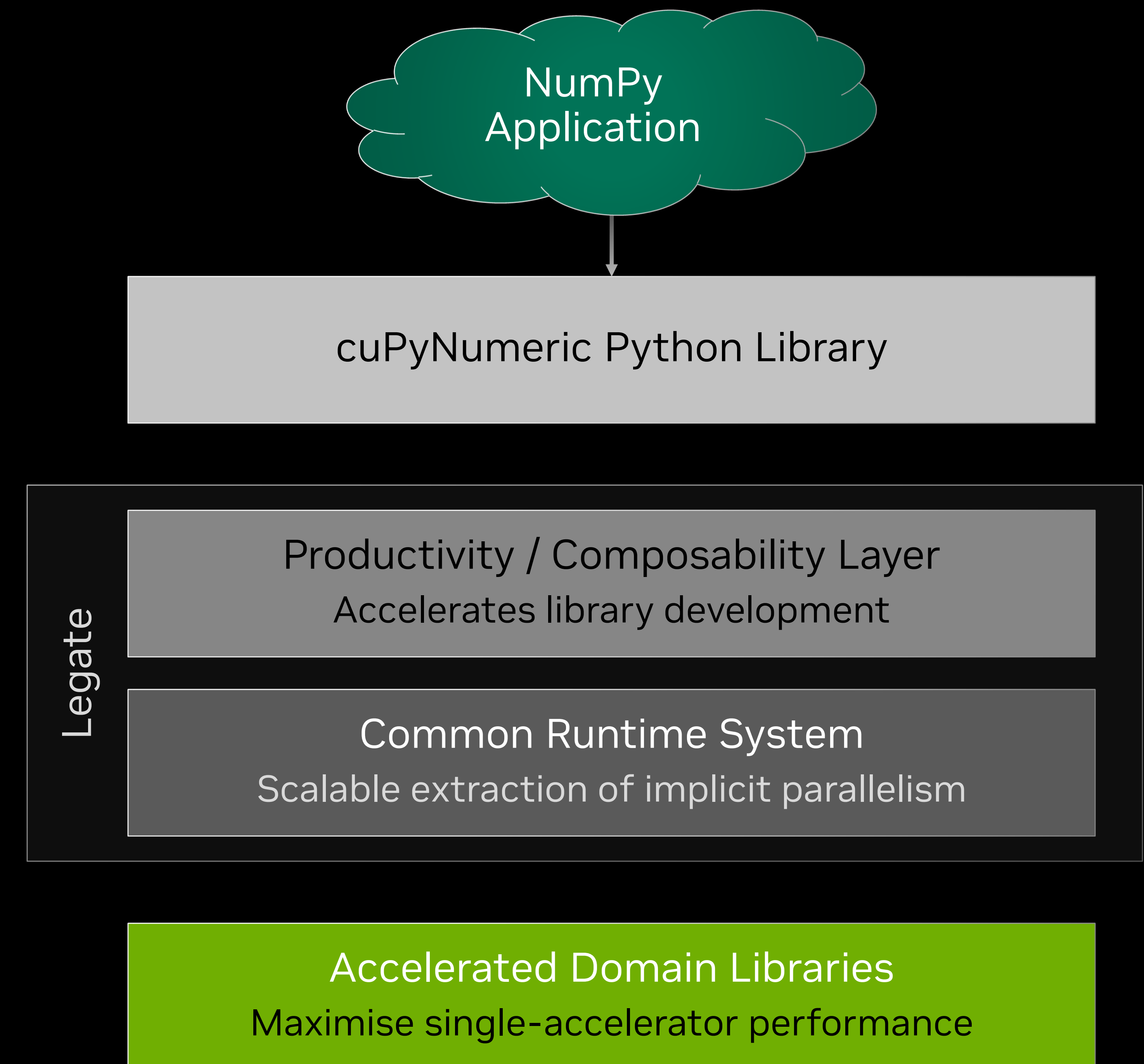
cuPyNumeric – Implicitly Parallel Implementations of NumPy APIs

[Developer blog: Effortlessly Scale NumPy from Laptops to Supercomputers with NVIDIA cuPyNumeric](#)

Stencil Benchmark

No modifications required to scale to a thousand GPUs

```
32
33 def run_stencil(N, I, warmup, timing): # noqa: E741
34     grid = initialize(N)
35
36     print("Running Jacobi stencil...")
37     center = grid[1:-1, 1:-1]
38     north = grid[0:-2, 1:-1]
39     east = grid[1:-1, 2:]
40     west = grid[1:-1, 0:-2]
41     south = grid[2:, 1:-1]
42
43     timer.start()
44     for i in range(I + warmup):
45         if i == warmup:
46             timer.start()
47             average = center + north + east + west + south
48             work = 0.2 * average
49             center[:] = work
50     total = timer.stop()
51
52     if timing:
53         print(f"Elapsed Time: {total} ms")
54     return total
```



cuPyNumeric – Implicitly Parallel Implementations of NumPy APIs

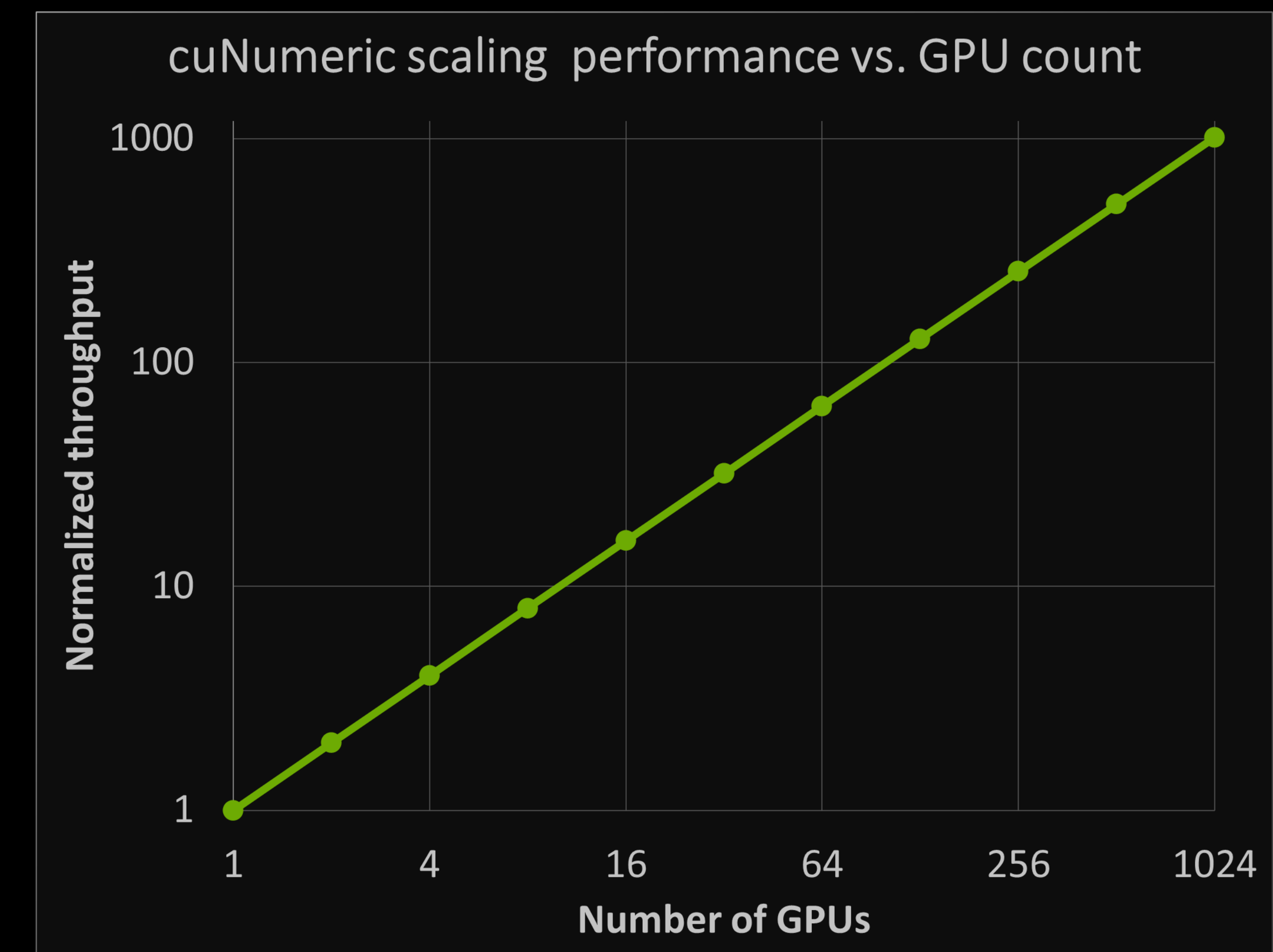
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46             timer.start()
47             average = center + north + east + west + south
48             work = 0.2 * average
49             center[:] = work
50     total = timer.stop()
51
52     if timing:
53         print(f"Elapsed Time: {total} ms")
54     return total
```

NumPy
Application



numba – Function Annotation and/or CUDA C-like Programming

ufunc example

Key Features

- Just-In-Time (JIT) Compilation – makes use of type specialisation
- Can accelerate CPU code as well as GPU code
- Works very well with NumPy ufuncs – element-wise operations ...

CPU

```
import numpy as np
from numba import vectorize

@vectorize
def saxpy(a, x, y):
    return a * x + y

a = 3.141
x = np.random.rand(1024, 2048)
y = np.random.rand(1024, 2048)

result = saxpy(a, x, y)
```

GPU

```
import numpy as np
from numba import vectorize

@vectorize([float32(float32, float32, float32)],
           target='cuda')
def saxpy(a, x, y):
    return a * x + y

a = 3.141
x = np.random.rand(1024, 2048)
y = np.random.rand(1024, 2048)

result = saxpy(a, x, y)
```

numba – Function Annotation and/or CUDA C-like Programming

kernel example

Key Features

- ... also allows CUDA-style kernels for more complex algorithms

```
import numpy as np
from numba import cuda

@cuda.jit(void(float32, float 32[:], float32[:], float32[:] ))
def saxpy(a, x, y, out):
    i = cuda.grid(1) # Shorthand for cuda.threadIdx.x + cuda.blockIdx.x * cuda.blockDim.x
    out[i] = a * x[i] + y[i]

a = 3.141
x = np.random.rand(1024*2048)
y = np.random.rand(1024*2048)

d_x = cuda.to_device(x) # Make a copy of x on the GPU
d_y = cuda.to_device(y) # Make a copy of y on the GPU
d_out = cuda.device_array_like(d_y) # Create an array shaped like y on the GPU

threads_per_block = 256
blocks = 1024*2048 / threads_per_block

# Launch a GPU kernel with an appropriate execution configuration
saxpy[blocks, threads_per_block](a, d_x, d_y, d_out)
cuda.synchronize()
```

PyCUDA – Kernel Programming

Key Features

- Python interface to CUDA
- Low-level access and fine-grained control
- Can write custom kernels in C/C++ directly within Python

```
import pycuda.autoinit
import pycuda.driver as cuda
import numpy as np
from pycuda.compiler import SourceModule

mod = SourceModule(""" # Compile the CUDA kernel code
__global__ void saxpy(int n, float a, float *x, float *y) {
    int i = blockIdx.x*blockDim.x + threadIdx.x;
    if (i < n) y[i] += a*x[i];
}
""")
saxpy_cuda = mod.get_function("saxpy") # Get the function pointer for the compiled kernel

a = 3.141
x = np.random.rand(1024*2048, dtype=np.float32)
y = np.random.rand(1024*2048, dtype=np.float32)

d_x = cuda.mem_alloc(x.nbytes) # Allocate memory for x on the GPU
d_y = cuda.mem_alloc(y.nbytes) # Allocate memory for y on the GPU
cuda.memcpy_htod(d_x, x)       # Copy data from CPU to GPU
cuda.memcpy_htod(d_y, y)       # Copy data from CPU to GPU

block_dim = (256, 1, 1)
grid_dim = ((1024*2048-1) // block_dim[0] + 1, 1)

# Launch the GPU kernel
saxpy_cuda(np.float32(a), d_x, d_y, n, block=block_dim, grid=grid_dim)

cuda.memcpy_dtoh(y, d_y) # Copy the results back to the CPU

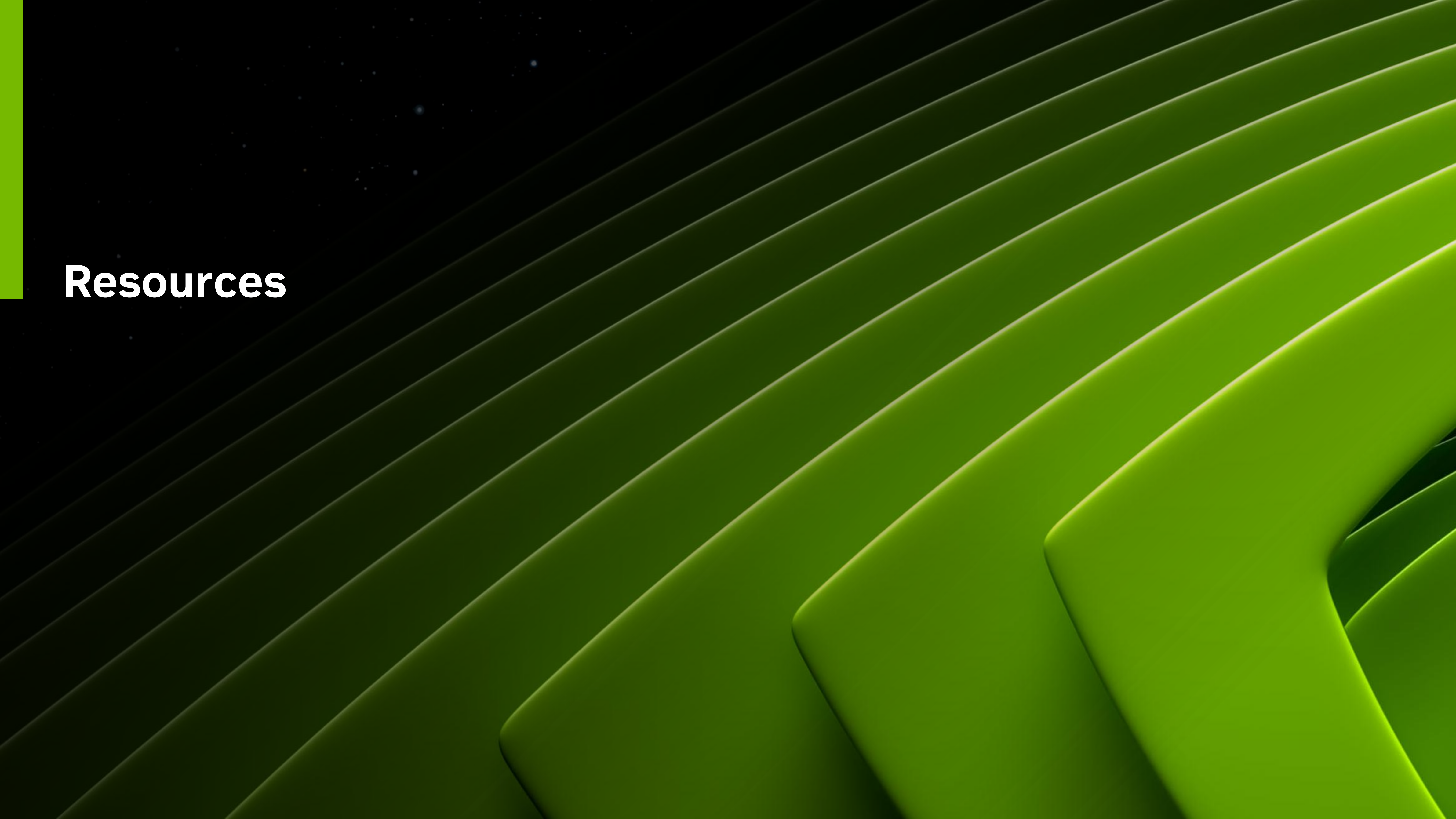
d_x.free() # Free GPU memory
d_y.free()
```

Future plans

- Move to a more “Pythonic” way of programming:
 - `cuda.core.experimental` ([github](#))
 - WeAreDevelopers [article](#)
 - 1,001 ways to write CUDA kernels in Python ([GTC talk](#))
- CUDA: New Features and Beyond ([GTC talk](#))

Useful Links

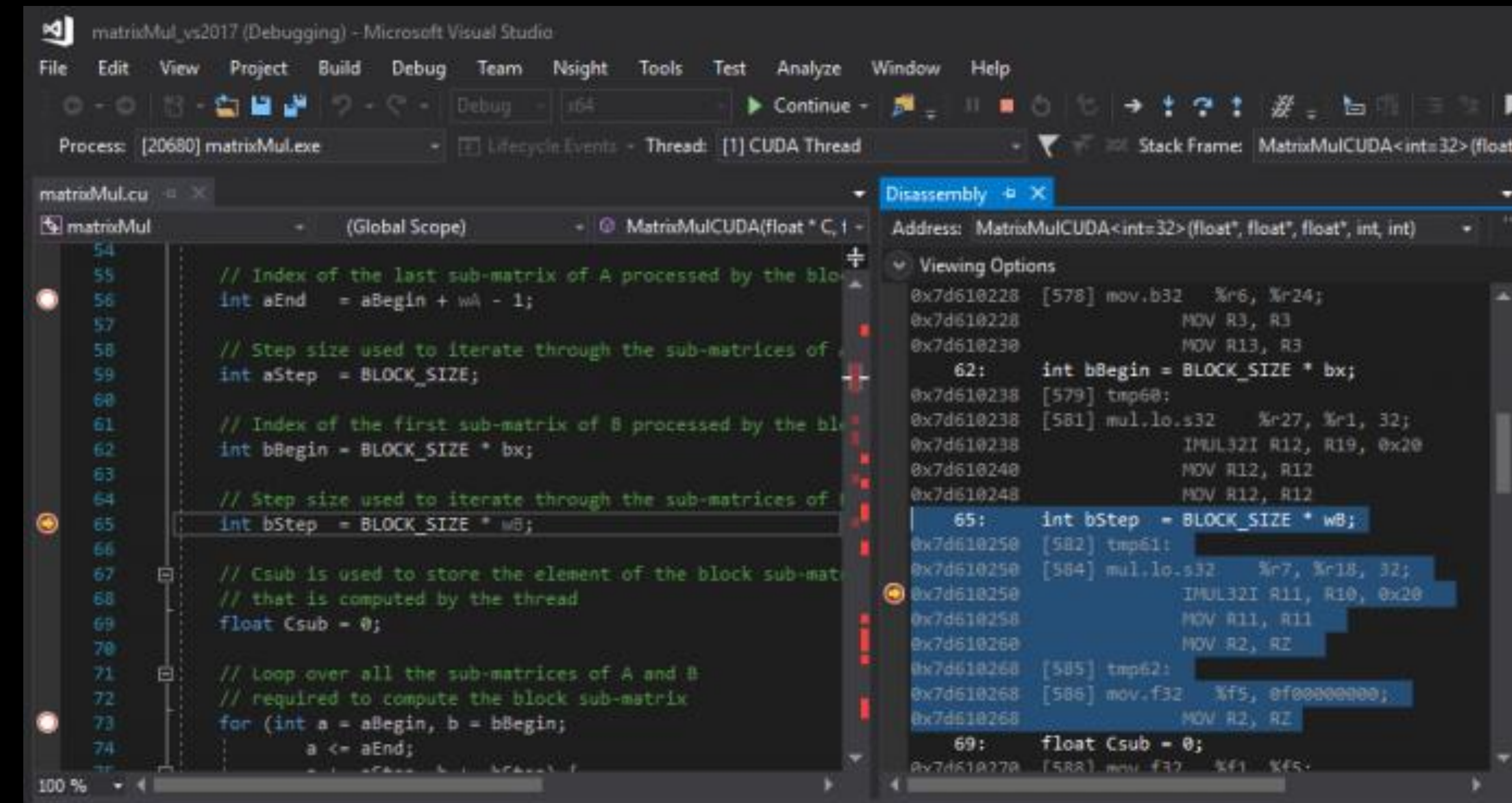
- Numba programming course
 - [Fundamentals of Accelerated Computing with CUDA Python](#)
- cuPyNumeric: <https://developer.nvidia.com/cupynumeric>
- Numba for CUDA GPUs: <https://numba.readthedocs.io/en/stable/cuda/index.html>
- CuPy: <https://cupy.dev/>
- PyCUDA: <https://pypi.org/project/pycuda/>



Resources

Developer Tools

Debuggers: cuda-gdb, Nsight Visual Studio Edition



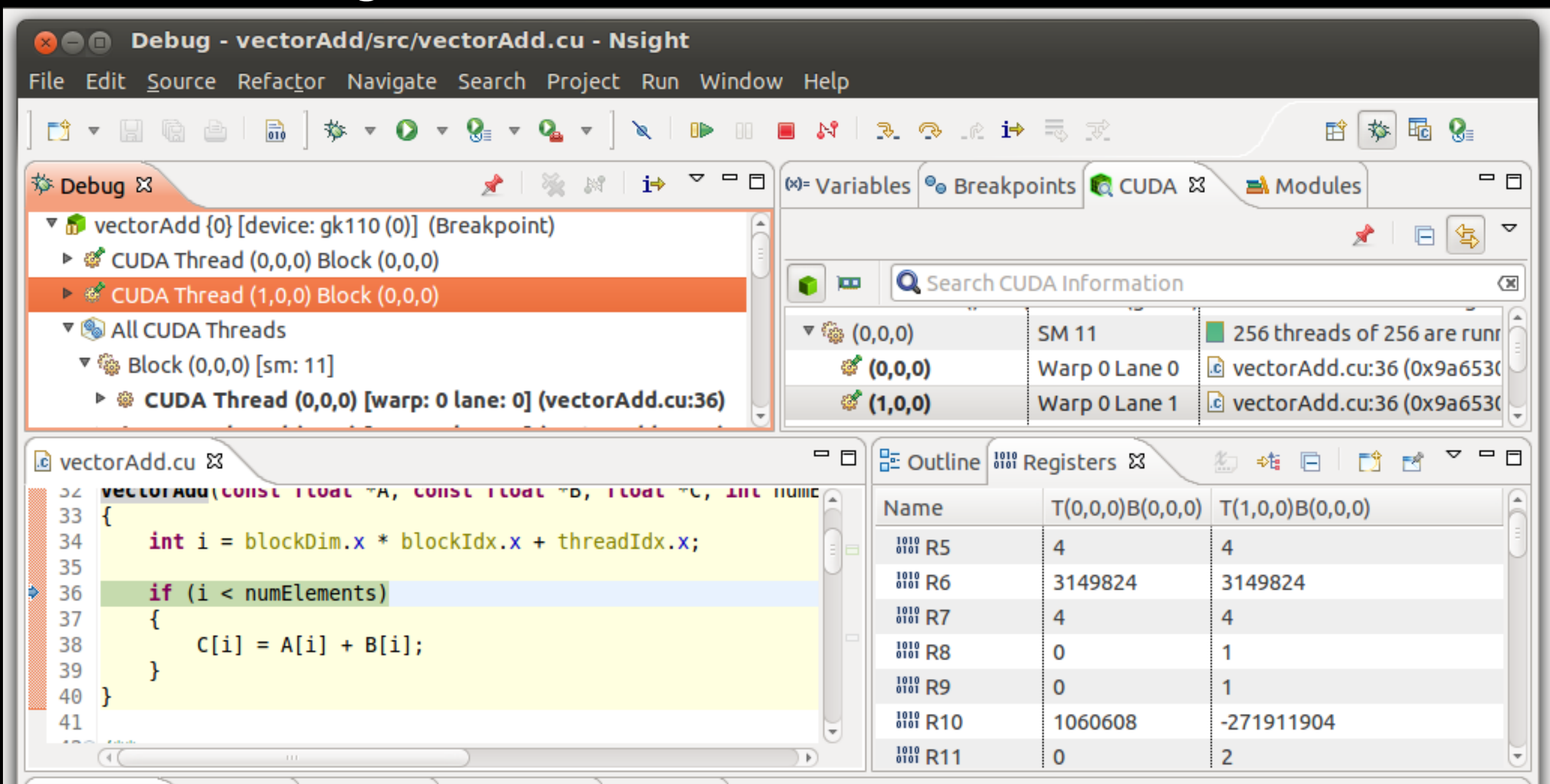
Profilers: Nsight Systems, Nsight Compute, CUPTI, NVIDIA Tools eXtension (NVTX)



Correctness Checker: Compute Sanitizer

```
$ compute-sanitizer --leak-check full memcheck_demo
===== COMPUTE-SANITIZER
Mallocing memory
Running unaligned_kernel
Ran unaligned_kernel: no error
Sync: no error
Running out_of_bounds_kernel
Ran out_of_bounds_kernel: no error
Sync: no error
===== Invalid __global__ write of size 4 bytes
===== at 0x60 in memcheck_demo.cu:6:unaligned_kernel(void)
===== by thread (0,0,0) in block (0,0,0)
===== Address 0x400100001 is misaligned
```

IDE integrations: Nsight Eclipse Edition
Nsight Visual Studio Edition
Nsight Visual Studio **C**ode Edition

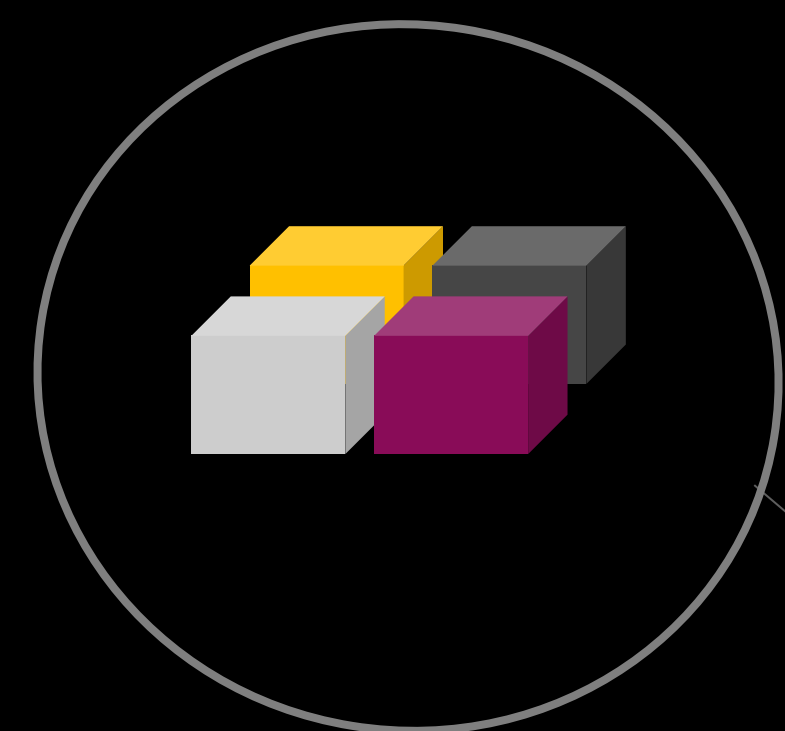


NGC: GPU-Optimized Software Hub

Simplifying DL, ML and HPC workflows

50+ Containers

DL, ML, HPC

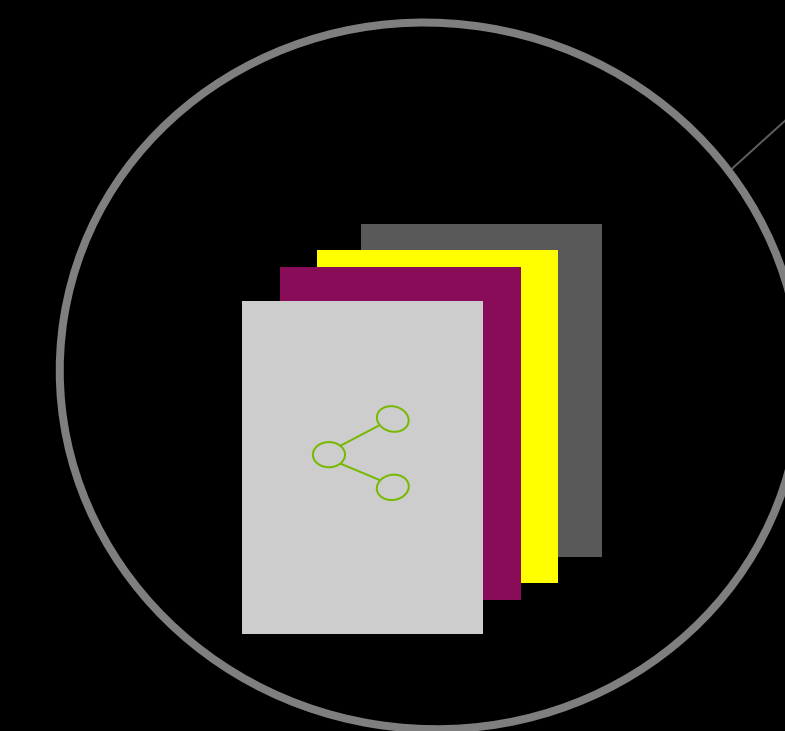


Model Training Scripts

NLP, Image Classification, Object Detection and more



NGC



60 Pre-trained Models

NLP, Image Classification, Object Detection and more



Workflows

Medical Imaging, Intelligent Video Analytics



DEEP LEARNING

TensorFlow | PyTorch | more



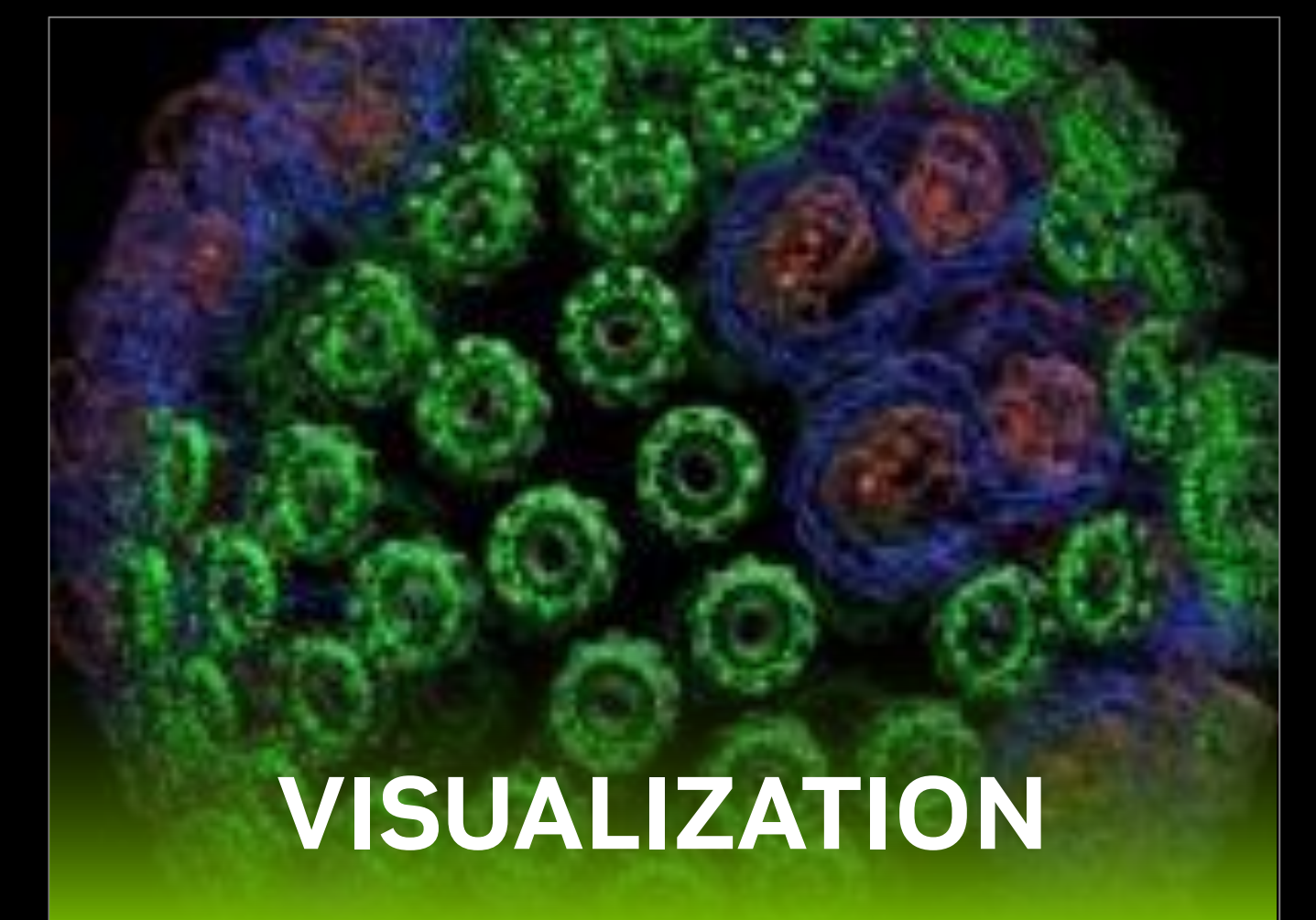
MACHINE LEARNING

RAPIDS | H2O | more



HPC

NAMD | GROMACS | more



VISUALIZATION

ParaView | IndeX | more

Deep Learning Institute (DLI)

Hands-on, self-paced and instructor-led training in deep learning and accelerated computing:

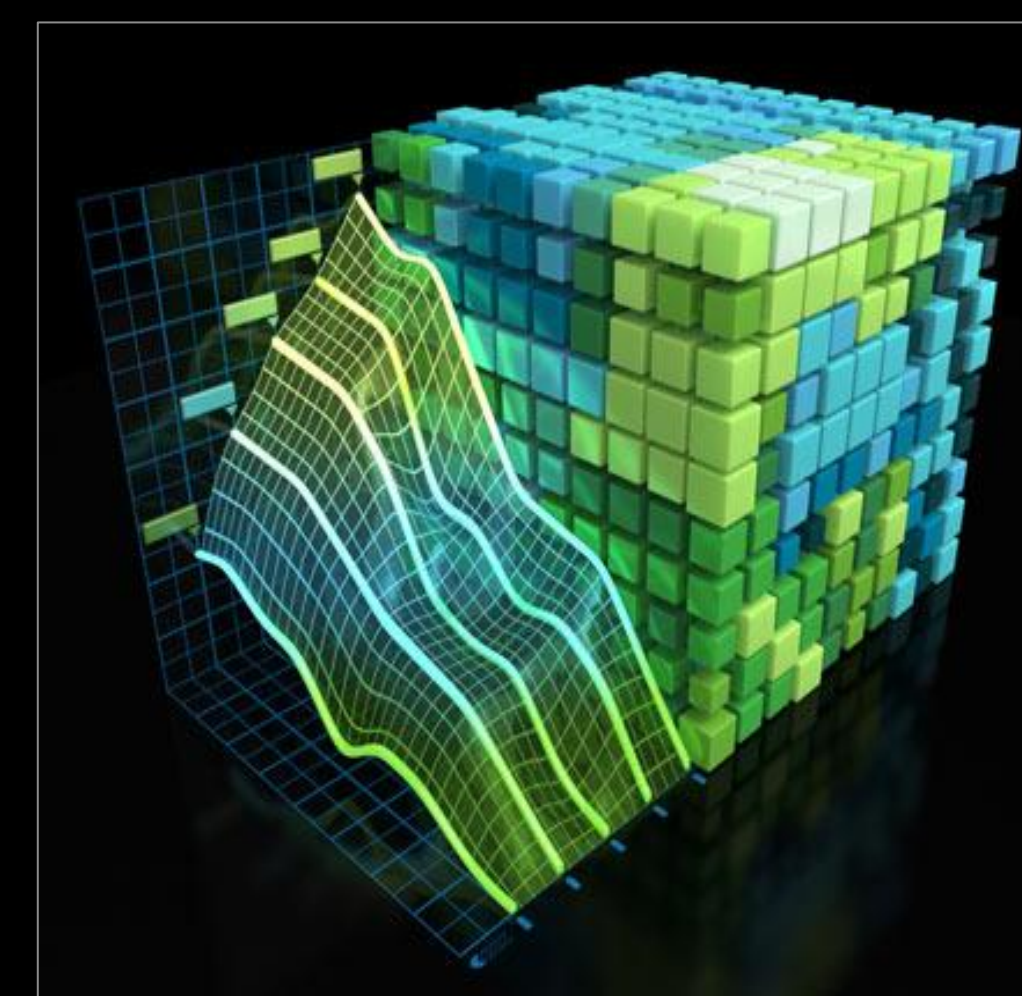
<https://www.nvidia.com/en-gb/training/>

NUMBA course:

[Fundamentals of Accelerated Computing with CUDA Python](#)

Lots of Python-based material:

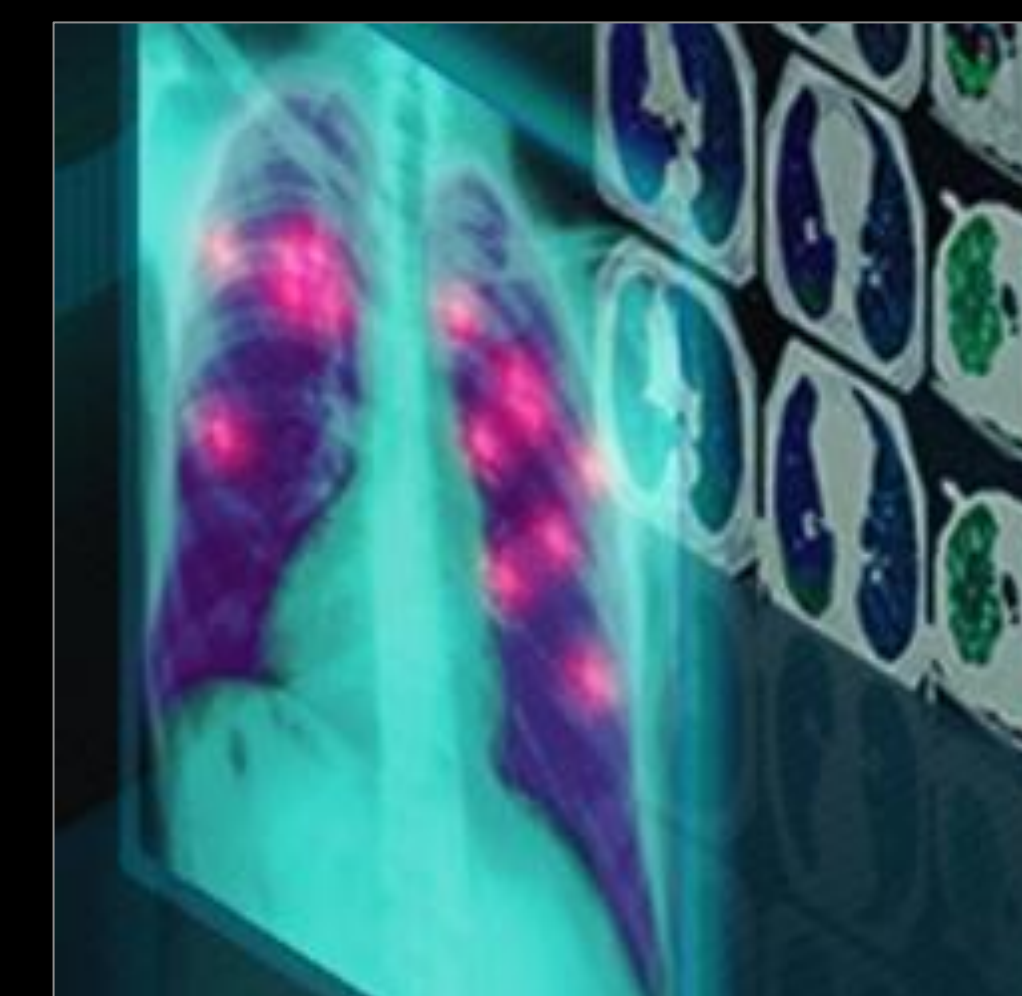
- [Accelerating End-to-End Data Science Workflows](#)
- [Get Started with Highly Accurate Custom ASR for Speech AI](#)
- [Introduction to Transformer-Based Natural Language Processing](#)
- [Introduction to Physics-Informed Machine Learning with Modulus](#)
- ...



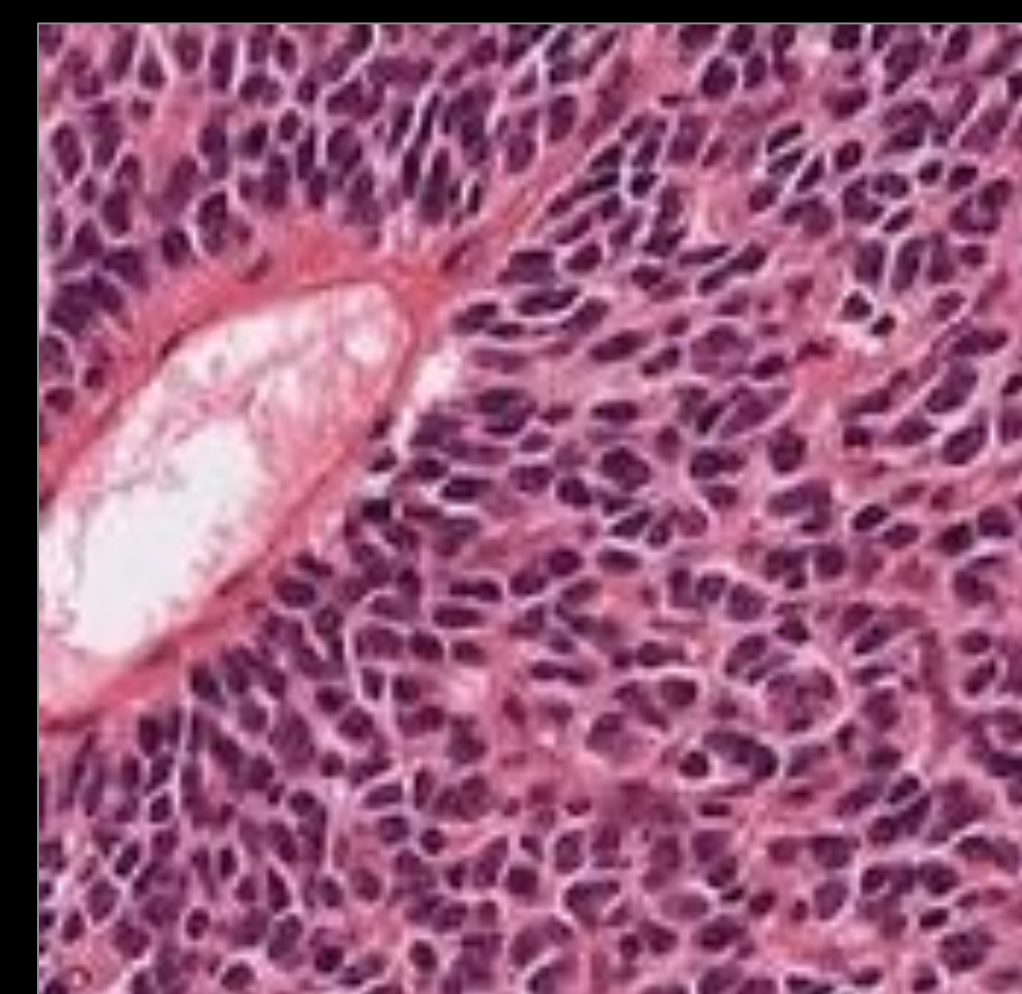
Accelerated Computing
Fundamentals



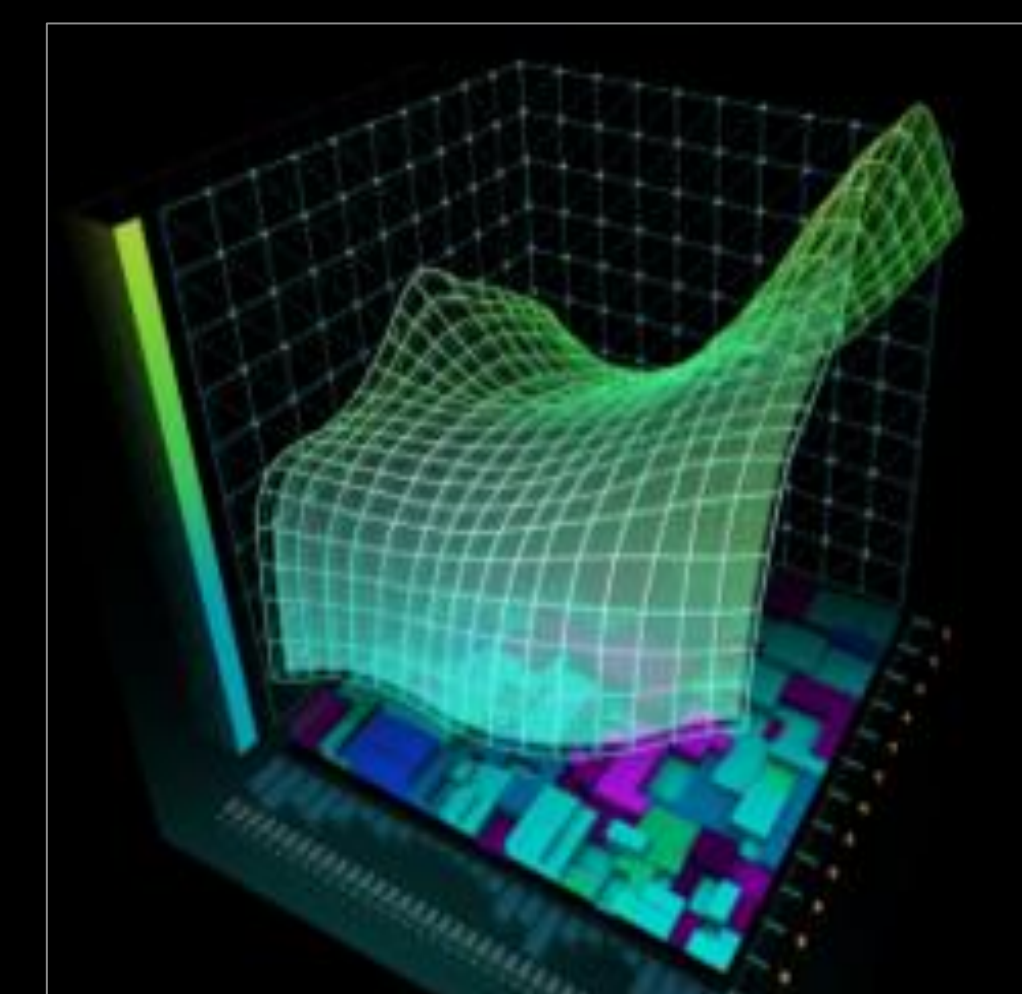
Autonomous Vehicles



Medical Image
Analysis



Genomics



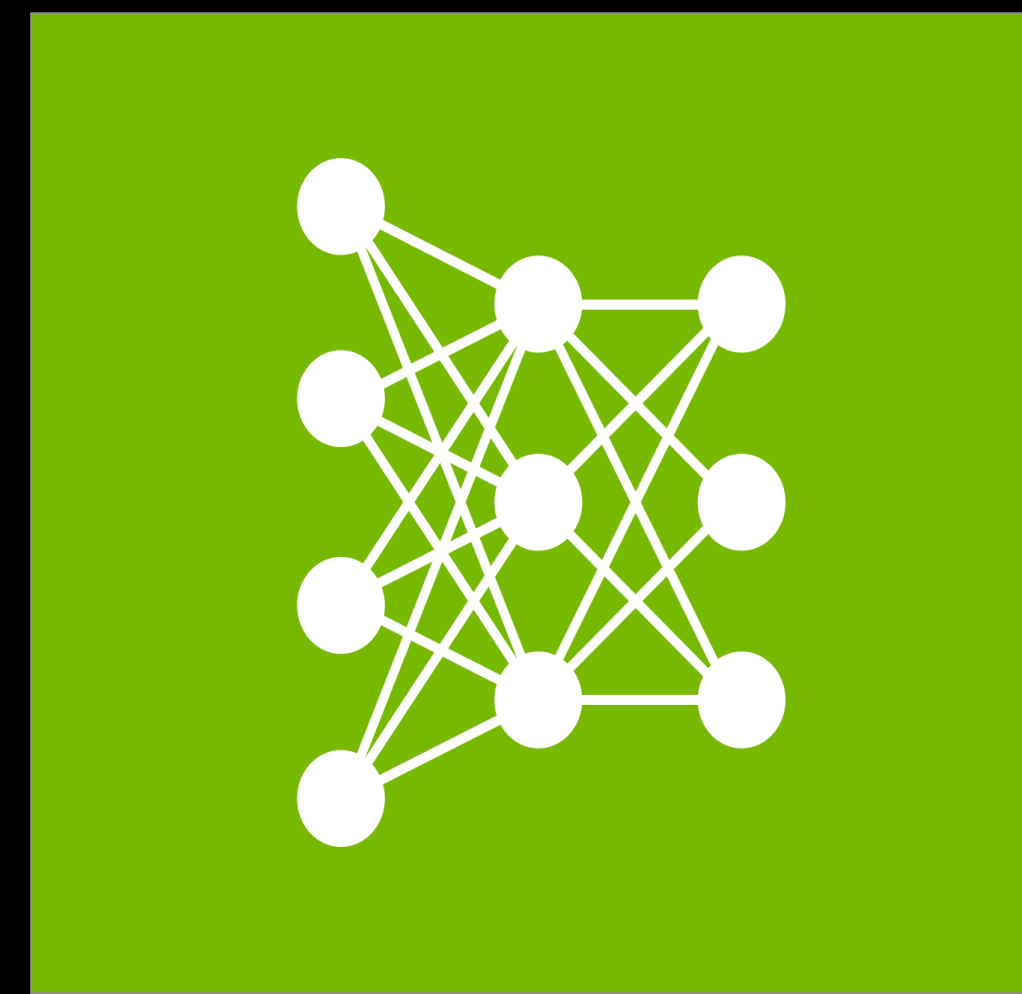
Finance



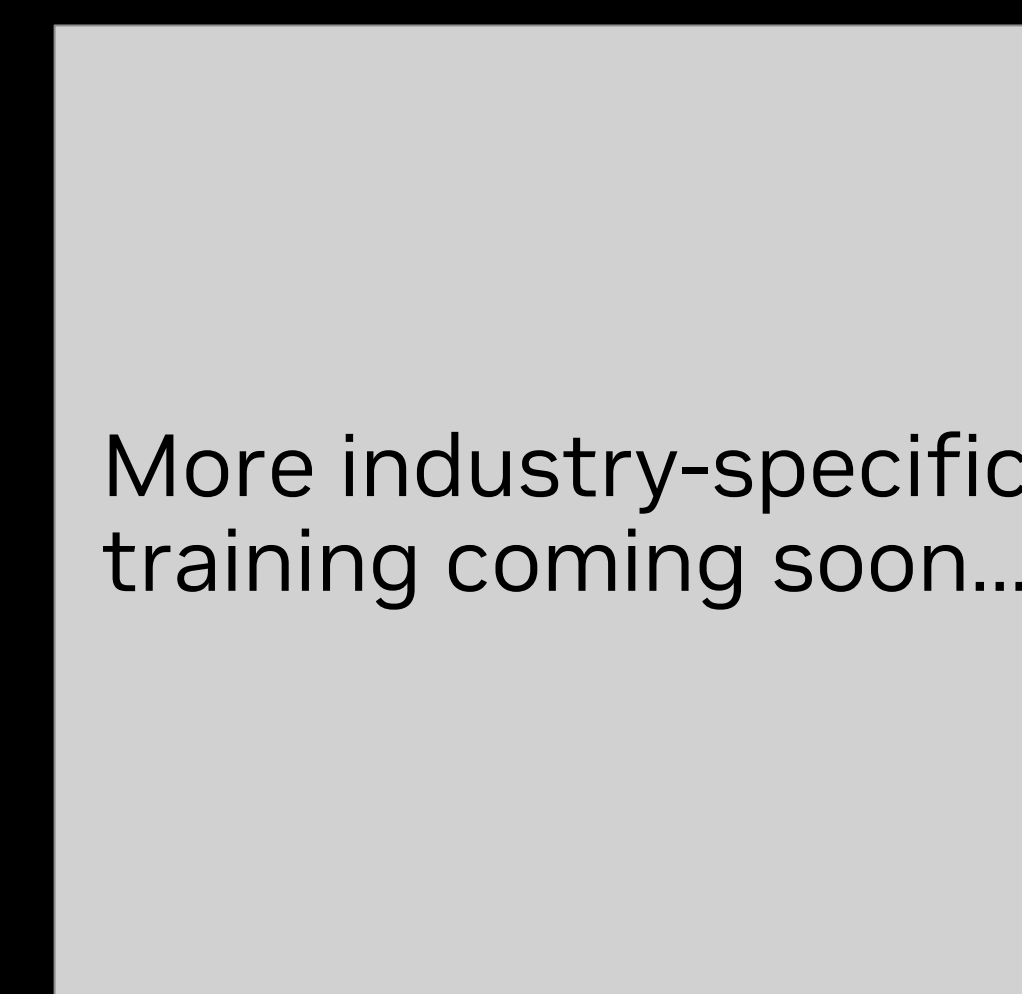
Content



Game Development



Deep Learning
Fundamentals



More industry-specific
training coming soon...



Thank you!

Accelerating Python on GPUs

Paul Graham, Senior Solutions Architect

pgraham@nvidia.com